



(AUTONOMOUS)

M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

TELECOMMUNICATION SWITCHING SYSTEMS AND NETWORKS

(Wireless and Mobile Communications)

Date: 23 July, 2014

Time: 3 hours

Max Marks: 60

1.	a)	Write the classification of Switching Systems and explain the elements of Switching System with a post diagram	6M
	b)	Explain the principles of Crossbar Switching.	6M
2.	a) b)	Explain in detail about distributed SPC (Stored Program Control). List the enhanced services made available to the subscribers because of the introduction of stored program control.	8M 4M
3.	a) b)	With neat block diagram explain Time Multiplexed Space Switching. Explain 2-Stage Combination Switching.	6M 6M
4.	a)	Explain three signaling forms involved in a telecommunication network and bring out the differences between inchannel and common channel signaling	6M
	b)	Explain the working principle of cellular mobile telephones.	6M
5.	a) b)	State the principles in Common Channel Signaling and Explain. Explain the CCITT Signaling System no.7 with necessary diagrams.	6M 6M
6.	a) b)	Explain Ring network and compare ring and bus networks. What is ATM? Mention the features of ATM.	6M 6M
7.	a) b)	Explain the lost call systems in the aspect of telecommunications traffic. A group of 20 servers carry traffic of 10 erlangs. If the average duration of a call is 3 minutes, calculate the number of calls put through by a single server and the group as a whole in a one hour period and the traffic intensity.	8M 4M
8.	a) b)	How the services of Integrated Services Digital Networks are used in Teletex. Write short notes on Broadband Integrated Services Digital Networks	6M 6M





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M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

DATA STRUCTURES AND ALGORITHMS

(Common to Computer Science and Engineering & Software Engineering)

Date: 28 July, 2014

Time: 3 hours

Max Marks: 60

Answer any Five Questions. All Questions carries equal marks. All parts of the question must be answered in one place only.

1.	a)	Consider the following infix expression	8M
		$(a+b\times(c+d)\times e+(f/g)-h)$	
		Convert the above given infix expression to prefix and postfix form.	
	b)	Write a 'C' program to convert an infix to prefix expression	4M
2.	a)	What does the following recurrence relation evaluates to?	6M
		T(0)=1, T(n)=T(n-1)+3n	
	b)	Which of the given options provides the increasing order of asymptotic complexity of	6M
		the functions? f_1, f_2, f_3 and f_4 ?	
		$f_1(n) = 2^n, f_2(n) = n^{n-2}, f_3(n) = n \log_2 n, f_4(n) = n \log_2 n^2$	
3.	a)	Given the preorder write the in order and post order. Also draw the corresponding	8M
0.	۷,	tree for the same	0
		Pre order : 12 41 68 91 72 43 11 64 75 90	
	b)	Differentiate between Binary tree and Binary search tree.	4M
4.	a)	Consider the following tree. Write the inorder, preorder and postorder traversal	7M
		techniques.	
		(75)	



b) In the above given tree as shown in Fig.1, find the following:

5M

ii. Depth of tree

i.

iii. Number of leaf nodes

Height of tree

- iv. Number of nodes
- v. Number of sub trees

5.	Expl i. ii.	ain in detail the operation and application of following Splay tree AVL tree	12M
6.	a)	With relevant steps, sort the following elements using a merge sort technique: 61, 45, 49, 68, 79, 61, 39, 11, 90, 55, 39, 22	8M
	b)	Write a 'C' program to search for a given element using a binary search technique.	4M
7.	a) b)	Write a note on the travelling sales person problem. Consider the following instances of the 0/1 Knapsack problem $n = 3, m = 20, (p1, p2, p3) = (25, 24, 15)$ and $(w1, w2, w3) = (18, 20, 25)$. Find optimal solution.	6M 6M
8.	a) b)	What is 8 queen's problem? Give the solution space for the same. Define the term 'bound and branch'.	8M 4M

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			All	parts	oft	he	que	stio	n m	nus	t be	an	swe	ered i	in or	ne pla	ce on	ly.		
1.	a)	Show (P→Q	that:)∧(R– - ∩) ←)⇔ >(P	, (P∨	R)—;	¢Q	Ň												6M
	b)	Show	that (<pre></pre>	√Q((¬(x))=	>(x) ⇒(x)	P(x)	∨(∃x	x)Q	(x)									6M
2	a)	If $A =$	{1,2,3	3,4} a	nd I	8 = -	a, b), C,	$dig\}$, (det	term	ine	whe	ether	the	follow	ing fui	nctior	ns are	6M
		one-to $f = \{($	-one (1, <i>a</i>), (or onto $(2, a)$,). (3,b),(4	<i>,d</i>)	}												
	b)	$g = \{($ Prove I	(1, d), ((2,b), eon ho	(3, <i>a</i> ole p), (4 rinci	·, <i>c</i>)} ipal	that	in a	n gro	oup	of	61 pe	eople	e, at l	east 6	peopl	e wer	re borr	n 6M
3.	a)	Five p each c Find tl i.	erson of the ne tot At any	s ente m can al num one o	red lea\ ber of the	the veth ofw e7f	lift ne ca /ays loor:	cabi abin in v s	n or inde vhich	n th ep∉ n ea	ne gr ende ach c	rou entlj of t	nd fl y at a he fiv	loor d any f ve pe	of ar floor erson	n 8 flo begin s can l	or hou ning v eave 1	use. S vith tl the ca	Suppos he firs Ibin	e 6M t.
	b)	ii. Prove Taken	At diff that t r at a	erent 1 he nur time,	floor nber $r \leq r$	rs rof η is	diffe s give	eren [†]	t per y	rmu	utati	ons	s of n	n disti	inct o	objects	5			6M
		${}^{n}P_{r} =$	$\frac{n!}{(n-1)}$	r)! = r	ı(n-	-1)	(<i>n</i> –	2).	(n·	- r	+1)).								
4.	a)	Solve	the re		ice r	elati	on:	•	0.0	$\langle 0 \rangle$		C	(1)	11						6M
	b)	S(k) Solve $b_n + 3$	-10.3 the re b_{n-1} +	(k-1) curren $2b_{n-2}$	(+9) ice rice rice $= 0$	elati witl	c−2 lon: h <i>b</i> ₁	2) = = -	0, S 2 ar	(U)	b = 3	,3(:4.	(1) =	11.						6M
5.	a)	Define i. / ii. S	e the f Alphal String	ollowi oet	ng te	erms	s wit	:h ar	ı exa	amp	ole fo	or e	each.							6M
	b)	iii. l Constr zero o	angu ruct ai ver th	age n NFA e alph	that abei	асс : {0	epts ,1}.	s all :	strin	ngs	such	ו th	at th	ne fift	th syi	mbol f	rom t	he lef	t end i	is 6M
6	a)	Constr	uct FA	to acc	cept	the	regi	ular	expr	ress	sion	(0+	1)*((00+1 ⁻	1)(0+	-1)*				6M
	b)	Show t	hat th	ie lang	uage	e L =	={a	^{i²} / i	≥ 1	is	not	reç	gular							6M
																		C	Cont2	2

7.	a)	Eliminate the left recursion from the following grammar: $E \rightarrow E + T T$ $T \rightarrow T * F F$	6M
	b)	$F \rightarrow (E) id$ What does each of the following transitions represent in PDA?	6M
		i. $\delta(p,a,Z) = (q,aZ)$.	
		ii. $\delta(p, a, Z) = (q, \varepsilon)$. iii. $\delta(p, a, Z) = (q, \varepsilon)$	
8	a)	Design a Turing Machine that accepts the set of all even palindromes over $\{0,1\}$.	6M
	b)	What is decidability? Explain any two undecidable problems.	6M

b) What is decidability? Explain any two undecidable problems.



(AUTONOMOUS)

M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

COMPUTER ARCHITECTURE AND ORGANIZATION

(Computer Science and Engineering)

Date: 23 July, 2014

Time: 3 hours

Max Marks: 60

1.	a)	Design a 4-bit binary subtractor and explain its functions.	6M
	b)	Simplify the function $F(A,B,C,D)=\Sigma(1,5,7,9)$ with don't cares $d(A,B,C,D)=\Sigma(4,6,8,10)$.	6M
2.	a) b)	What are the basic functional units present in the computer and explain each of them? By using the required parity generator/checker circuit, explain how parity checking can be used for the error detection.	4M 8M
3.	a)	Design a 4-bit common bus to transfer the contents of one register to other.	6M
	b)	Define 3-address, 2-address, 1-address, 0 -address instruction with an example.	6M
4.	a) b)	Explain the Booth Algorithm for multiplication of Signed two's Complement number. Discuss the various hazards that might arise in a pipeline. What are the remedies commonly adopted to overcome/minimize these hazards.	6M 6M
5.	a)	"Hard wired control is advantageous over micro programmed controller". Justify your answer with valid reasons.	6M
	b)	What is pipelining and what are the advantages of pipelining? Explain with suitable example.	6M
6.	a)	Discuss the address translation mechanism and the different page replacement policies used in a virtual memory system.	8M
	b)	Explain the operation of Associative cache memories.	4M
7.	a)	What is the importance of I/O interface? Explain the features of PCI Interfaces.	6M
	b)	Explain why is priority handling desired in interrupt controllers? How does the priority scheme work?	6M
8.	a)	Explain any two interconnection topologies? Compare the factors determining the performance and the cost of both the networks.	6M
	b)	What do you mean by inter process arbitration? Explain how it is implemented in multiprocessor architecture.	6M

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	VARDHAMAN COLLEGE OF ENGINEERING (AUTONOMOUS) M. Tech I Semester Supplementary Examinations July - 2014 (Regulations: VCE-R11) SOFTWARE ENGINEERING (Computer Science and Engineering)																				
Date	Date: 24 July, 2014 Time: 3 hours Max Marks:													ks: 60							
Answer any Five Questions. All Questions carry equal marks. All parts of the question must be answered in one place only.																					
1.	a) b)	Expla Brief	ain fly	the exp	e so Iain	ftwa i the	re e pro	engir cess	neeri flov	ng l v m	aye ode	ers in el.	ı deta	nil.							6M 6M
2.	a)	Expla	ain	wh	ıy p	rogr	ams	s tha	it ar	e de	evel	lope	d usi	ng evol	utionar	y devel	opmer	nt are	e likel	y to	4M
	 be difficult to maintain. b) Giving reasons for your answer based on the type of system being developed, suggest the most appropriate generic software process model that might be used as a basis for managing the development of the following systems: A system to control anti-lock braking in a car A virtual reality system to support software maintenance A university accounting system that replaces an existing system An interactive system that allows railway passengers to find train times from terminals installed in stations 											8M									
3.	a) b)	lden Expla	tify ain	/ fur bri	ncti efly	onal Clas	and ss Re	l no espo	n fui nsib	nctio ility	ona Co	l req Ilabo	juirer prato	nents fo r model	or auto I with a	mation n exam	of ATN ble.	Л.			6M 6M
4.	a)	Expla	ain	W	hy	it r	nay	be ton	neo	cess	ary	to	desi	gn the	syster	m arch	tectur	e be	fore	the	6M
	b)	Expla	ain	the	e Ot	oject	Ori	ente	d Aı	chit	tect	ure	Mode	el and it	ts advai	ntages.					6M
5.	a)	Assu Iden svste	ime tify em	e th / ar	at y	you expla	hav ain	e be brie	en a fly t	aske he	ed t use	to de er in	evelo terfa	p an or ce desig	nline m gn issu	ovie tic ies invo	ket bo Ived v	ooking vith t	g syst the gi	em. iven	6M
	b)	Expla	ain	the	e de	sign	heu	iristi	cs fo	or ef	ffec	tive	mod	ularity.							6M
6.	a) b)	Wha Wha	nt d nt d	o yo o yo	n uc n uc	meai meai	n by n by	syst test	tem t cas	test e de	ing esig	? Exj n? E	plain xplai	the dist n the va	tinct ph rious a	ases of pproacl	systen 1 of te	n test st cas	ing. e des	ign.	6M 6M
7.	a) Explain the concept of path testing with suitable example.b) Explain the concept of black box testing.											6M 6M									
 8. a) Describe three types of software process metric that may be collected as part of a process improvement process. b) Explain why a high-quality software process should lead to high-quality software products. Discuss possible problems with this system of quality management. 											6M 6M										

Hall 1	Ticke	et No: Question Paper Code :	B1207										
		VARDHAMAN COLLEGE OF ENGINEERING (AUTONOMOUS) M. Tech I Semester Supplementary Examinations July - 2014 (Regulations: VCE-R11)											
Date	(Common to Computer Science and Engineering & Software Engineering) Date: 25 July, 2014 Time: 3 hours Max Marks: 6 Answer any Five Questions All Questions carry equal marks												
		Answer any Five Questions. All Questions carry equal marks. All parts of the question must be answered in one place only.											
1.	a)	Image of size 512 x 512 pixels / frames are encoded to 8 bits / pixel and are transmitted after compression at a ratio of 4. Transmission is at 25 frames / second.	6M										
	b)	Explain uniform / non-uniform type of: i. Sampling ii. Quantization	6M										
2.	a)	Prove the following property: i. Imaginary part of Fourier transform of even function is zero ii Convolution	6M										
	b)	Write short notes on orthogonal transforms.	6M										
3.	a)	Define smoothing. Prove that order statistic filtering commutes with any linear monotonically increasing transformation.	6M										
	b)	Gray level histogram of output image obtained is given below:	6IVI										
		Gray Level 0 1 2 3 4 5 6 / Frequency 400 700 1350 2500 3000 2500 550 0											
		Compute grey level histogram of output image obtained by enhancing the input by histograms equalization techniques.											
4.	a)	Explain briefly how an iterative non linear restoration functions using Lucy- Richardson algorithm with an example.	6M										
	b)	Name and comment on simplest approach followed to restore a degraded image to its form back.	6M										
5.	a)	Give the relation to choose threshold generally. Elaborate on terms global, local and dynamic threshold.	6M										
	b)	Give the algorithmic steps for contour based boundary detection with a neat diagram.	6M										
6.	a)	Find Huffman coding for the following to get the minimum average length.	7M										
		Symbol Probability											
		a2 0.4 a3 0.3											

0.15 a4 b) Explain vector quantization compression.

a1

0.15

- 7. a) Compute the value of a Gaussian PDF, N(m, s) at $x_1 = \begin{bmatrix} 0.2, 1.3 \end{bmatrix}^T$ and 4M $x_2 = \begin{bmatrix} 2.2, -1.3 \end{bmatrix}^T$ where $m = \begin{bmatrix} 0, 1 \end{bmatrix}^T$, $S = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$.
 - b) Consider a 2 class classification task in 3 dimension space where 2 classes w1 and w2 8M are modeled by Gaussian distributions with means $m_1 = [0, 0, 0]^T$ and $m_2 = [0.5, 0.5, 0.5]^T$ respectively. Assume the two classes to be equi-probable. The covariance matrix for both distributions S is given below:
 - $S = \begin{bmatrix} 0.8 & 0.01 & 0.01 \\ 0.01 & 0.2 & 0.01 \\ 0.01 & 0.01 & 0.2 \end{bmatrix}$

Given a point $x = [0.1, 0.5, 0.1]^T$ classify x according to:

- i. Euclidian distance
- ii. Manhattan distance classifier
- 8. a) Explain maximum likelihood parameter estimation method and its properties.
 6M
 b) Explain working of Naïve Bayesian classifier with an example.
 6M



(AUTONOMOUS)

M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

C# AND .NET FRAMEWORK

(Common to Computer Science and Engineering & Software Engineering)

Date: 26 July, 2014

Time: 3 hours

Max Marks: 60

1.	a)	What are the various forms of the Main() method that are permissible in a C# executable application?	6M
	b)	Bring out the core distinctions between value type and reference type in C# with examples.	6M
2.	a) b)	Discuss with an example how encapsulation is enforced in C# with the help of properties. Illustrate with an example how polymorphism is supported in C#.	6M 6M
3.	a)	With the help of code snippets demonstrate the following exceptions: i. ArgumentOutofRange ii. IndexOutofRange	6M
	b)	Write a C# program to implement the core members of the System.Exception type.	6M
4.	a) b)	Illustrate the use of delegates in C# events. With an example explain the use of callback interfaces.	6M 6M
5.	a) b)	Illustrate how a multifile assembly can be built and consumed. Briefly explain the process/AppDomain/Context/Thread relationship.	7M 5M
6.	a) b)	With an example explain how asynchronous remoting can be performed? What are the different ways in which remote objects can be hosted? Explain briefly?	6M 6M
7.	a)	Demonstrate with the help of C# code snippets how mouse events and keyboard events	6M
	b)	Illustrate with an example how to work with some basic controls on the forms.	6M
8.	a) b)	Discuss the disconnected layer of ADO.Net. Demonstrate how a data relation object can be used to a relationship between two tables for an order placement application and also show how data can be fetched in the master-detail format.	5M 7M

(AUTONOMOUS)

M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

OBJECT ORIENTED ANALYSIS AND DESIGN

(Software Engineering)

Date: 22 July, 2014

Time: 3 hours

Max Marks: 60

1.	a) b)	Describe object identity, encapsulation and polymorphism. List the common mechanisms that can be applied for Unified Modeling Language (UML). Explain any two.	6M 6M
2.	a) b)	 Compare association, aggregation and composition with example. Categorize the following relationships into generalizations, aggregation or association and draw the diagram A country has a capital city Modems and keyboards are input/output devices A student takes a course from a professor 	6M 6M
3.	a)	Illustrate with an example, how to model a flow of control by time ordering using	6M
	b)	sequence diagram. Explain the following with regard to interaction diagrams: i. Object Life Line ii. < <create>> and <<destroy>> messages iii. focus of control</destroy></create>	6M
4.	a)	Explain the relationships between the use cases with an example.	5M
	b)	Describe time and change event. Draw a chart diagram for a phone line.	7M
5.	a)	Discuss the differences between classes and components.	6M
	b)	With an example show how to model distribution of components.	6M
6.	a)	Explain the different ways that a use case can be realized during analysis phase.	6M
	b)	Discuss the need to have architecture for software systems.	6M
7.	a)	Explain the core work flows will be carried out during the inception phase.	8M
	b)	Explain the activities involved during the initial stage of elaboration phase.	4M
8.	a)	Explain the activities that to be carried out during transition phase.	8M
	b)	Describe the archetypal construction iteration workflow.	4M



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1.	a)	Draw practi practi i.	the V- ical co ical co BJT	l chara nditior nditior	acter 1s. A 1s) d	istic Iso, iffer	s of expl fror	the ain v m ea	fol wh <u>y</u> ach	llowi y the oth	ng de e two er.	evi o cł	ces un haracte	der id eristics	eal cond s (under	ditions ideal a	and and		8M
	b)	ii. Ment	Thyris ion th	tor e chara	acter	istic	s wł	nich	are	e des	sired	in	a powe	er swi	tching c	levice.			4M
2.	a)	Defin i. ii.	e: Avalaı Punch	nche bi throu	reak gh ve	dow oltag	'n, ge,												6M
	b)	III. Briefly	Zener y expla	breako ain abc	dowi but F	n. ast l	Recc	overy	y D	iode	S.								6M
3.	a) b)	Explai Briefly	in the y expla	structu ain sec	ure o onda	of a p ary b	oow oreal	er B. kdov	JT \ wn	with in re	a nea elatio	at on f	diagrar to a po	m. wer tr	ransisto	r.			8M 4M
4.	a)	What norm	kind al ope	of effe	ect of f	lo t the	he p devi	oara: ice?	siti Sh	c ca now,	pacit in t	an he	form	a pov diagra	wer MC am, hov	SFET I v the	have (struct	on the ure of	8M
	b)	A circ drive	the po	ployin wer N	ig M 10SF	OSF ET a	ETs (and b	cons	sist fly e	of r expla	esisti ain th	ive	e load. drive ci	Sugge ircuit	est a sim operatio	nple dri on.	ive cir	cuit to	4M
5.	a) b)	With What	a neat are th	diagra ie caus	am e ies o	xpla f lat	in th ch-u	ne st ip in	truc an	cture I IGB	e of a T? Ho	in l ow	IGBT. / it can	be av	oided?				6M 6M
6.	a) b)	Explai Discu	in the ss the	unique metho	enes: ods u	s of sed	a th for i	yrist impr	or rov	usin ing t	g its ' he <i>d</i> i	VI li/d	charac It rating	teristi gs of a	cs. a thyrist	or.			6M 6M
7.	a)	Explai	in ho	w the	cor	nduc	tion	an	d	tran	sitior	۱I	losses	can l	be com	puted	in th	nermal	6M
	b)	Draw semic	the el	ectrica ting de	II equ evice	uiva e and	lent d exj	circ plair	uit า.	of tł	ne the	err	mal mc	odel re	elated to	а ром	/er		6M
8.	a)	Write i.	short Steel	notes	on t	he f	ollov	wing	j fe	rron	nagne	etio	c mate	rials:					6M
	b)	An ai 1.5mr inner possil	r core m thic diame ole to	induc k. For eter of attain	tanc cool 60 n requ	e of ing nm a ired	50 purp and ind	μΗ bose an o ucta	is e, ½ oute ance	mad 2 mr er di e.	e as n spa amet	wo acii ter	ound s ng is u [•] of 160	strip o sed b)mm a	of coppe etween as physic	er 40m each 1 cal con	m wid turn w strain	de and vith an ts. Is it	6M

Hall 1	icket No: Question Paper Code :	B1302
	VARDHAMAN COLLEGE OF ENGINEERING	
	(AUTONOMOUS)	
	IVI. Tech i Semester Supplementary Examinations July - 2014 (Regulations: VCF-R11)	
	PRINCIPLES OF MACHINE MODELING ANALYSIS	
	(Power Electronics and Electric Drives)	
Date:	22 July, 2014 Time: 3 hours Max Ma	rks: 60
	Answer any Five Questions. All Questions carry equal marks. All parts of the question must be answered in one place only.	
1.	a) Explain the principle of rotating magnetic field.b) Explain the power angle characteristics of non salient pole synchronous motor with neat sketch.	6M 6M
2.	Discuss briefly the primitive forms of various machines.	12M
3.	A separately excited d.c motor is at rest, with its field winding carrying a steady state current I_f . The motor and load has a total inertia of J kg m ² . Load torque, damping and armature inductances are negligible. If voltage V_t is suddenly impressed across the armature, find the total heat energy dissipated in the armature resistance as the motor accelerates from rest to final steady speed W_r . Does this energy loss depend upon acceleration time or final no load speed W_r .	12M
4.	 a) Explain Linear Transformation with examples. b) Explain the phase transformation technique a,b,c to α,β,0. 	6M 6M
5.	For a three phase induction motor write the voltage and current equations in stator reference frame.	12M
6.	Draw the generalized mathematical model of a polyphase induction machine and write down the voltage equations for this model and hence obtain the equivalent circuit of a poly phase induction motor.	12M
7.	Derive the dynamical equation of induction machine during normal operation and thereby explain motor dynamics for:	12M

- i. Change in K with constant load torqueii. Change in load torque with constant K
- a) Derive the torque equation of a 3 phase synchronous motor.b) Develop the state space voltage- current equation of synchronous machine. 8. 6M 6M



(AUTONOMOUS)

M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

POWER ELECTRONIC CONVERTERS-I

(Power Electronics and Electric Drives)

Date: 23 July, 2014

Time: 3 hours

Max Marks: 60

- 1. With neat circuit diagrams and relevant waveforms, discuss about the ON-OFF control and 12M phase angle control methods of 1-phase AC voltage controllers .
- 2. With a neat circuit diagram, explain the operation of 3-phase bidirectional delta connected 12M (R-load) AC voltage controller operating at α =120⁰. Obtain any two phase currents and any one line current waveforms.
- a) What is Matrix converter? Explain in detail.
 b) Explain the operation of three-phase to three-phase cycloconverter (6-pulse) with 6M relevant circuit diagram and wave forms?
- 4. a) Explain the operation of single phase controlled converter with its neat wave forms.
 b) What are the applications of single phase converters?
 4M
- 5. With relevant voltage and current waveforms, explain the operation of three-phase halfconverter feeding R-L load for $\alpha = 60^{\circ}$. Assume continuous current in load. Derive an expression for average and rms values of output voltage.
- 6. a) Explain the operation of a boost regulator assuming continuous conduction mode. 6M
 - b) With a neat equivalent circuits and relevant waveforms, explain the operation of Cuk 6M regulator converter.
- 7. a) Discuss in brief about the Delta modulation technique of voltage control of 1-phase 6M inverter.
 - b) Explain the operation of a 1-phase full bridge inverter with neat waveforms. 6M
- 8. Explain 180^o conduction mode operation of 3-phase inverter and draw the relevant 12M waveforms.

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M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

POWER ELECTRONIC CONTROL OF DC DRIVES

(Power Electronics and Electric Drives)

Date: 24 July, 2014

Time: 3 hours

Max Marks: 60

Answer any Five Questions. All Questions carry equal marks. All parts of the question must be answered in one place only.

- a) With a neat circuit diagram and relevant waveforms, explain the operation of single 8M phase semi converter fed separately excited DC drive system. Derive an expression for average value of output voltage. Assume continuous current in load. Also draw input current waveform.
 - b) An ideal single-phase supply 230 V, 50 Hz, provides power for a fully controlled bridge 4M converter supplying a separately excited DC motor rated at 1 kW, 200 V, 800 RPM. The motor has armature resistance and inductance 0.4 Ω and 5 mH respectively. If the motor delivers rated power at rated speed with $\alpha = 0^{0}$, calculate the power factor of the converter.
- a) When do you prefer three-phase rectifier fed DC drive system? With neat sketch and waveforms, explain the operation of three-phase full-wave converter operating with 30⁰ firing angle. Assume continuous current operation.
 - b) The speed of a 20 HP, 300 V, 1800 RPM separately excited DC motor is controlled by a three-phase full-converter drive. The field current is also controlled by a three-phase full converter and is set to the maximum possible value. The Ac input is a three-phase, star-connected, 208 V, 60 Hz supply. The armature and field resistances are 0.25 Ω and 245 Ω respectively, and the motor voltage constant is $K_{\nu} = 1.2$ V/A rad/s. The armature and field currents can be assumed to be continuous and ripple free. Determine delay angle of the armature converter, if motor supplies a rated power at rated speed.
- 3. a) Power is transferred from a 300 V battery to a three-phase, 230 V, 50 Hz, AC bus via a 6M controlled SCR inverter. The inverter switches may be considered lossless and a large filter inductor with resistance of 10 Ω is included on the DC side. Calculate the power transferred for the power factor of (a) α =90⁰, (b) α =120⁰.
 - b) Write a short note on three phase controlled bridge rectifier feeding passive load 6M impedance.
- 4. Explain the Speed torque Characteristics of a dc series motor connected to a three phase 12M fully controlled converter.
- 5. a) Discuss in brief about the first-order approximation of inner current loop control of DC 8M motor.
 - b) Discuss in brief about the filter in the speed feedback loop of DC motor drive. 4M

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- 6. a) Explain the principle of speed control of a dc motor and show how it can be achieved by 6M a chopper.
 - b) A 230V, 1200rpm, 15A separately excited motor has an armature resistance of 1.2Ω.
 6M Motor is operated under dynamic braking with chopper control. Braking resistance has a value of 20 Ω.
 - i. Calculate duty ratio of chopper for motor speed of 1000rpm and braking torque equal to 1.5times rated motor torque.
 - ii. What will be the motor speed for duty ratio of 0.5 and motor torque equal to its rated torque?
- 7. Draw and explain the power circuit diagram of semi-converter feeding a separately excited 12M D.C motor. Explain with typical voltage and current waveforms, the operation in continuous armature current Mode.
- Determine the speed-controller gain and time constant for the following separately excited 12M chopper-controlled DC motor drive.
 250 HP, 500 V, 1250 RPM, 92% efficiency, R_a = 0.052 Ω, L_a=1 mH, K_b=3.65 V/rad/sec, J = 5 kg.m2, B₁ = 0.2 N.m/rad/sec, V_s =648 V. The current controller has a PWM strategy with a carrier frequency of 2 kHz. Calculate also the speed response for a speed command of 0 to 0.8 pu, when the load torgue is maintained at 0.5 pu.



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M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

ADVANCED MICRO PROCESSOR AND MICRO CONTROLLERS

(Power Electronics and Electric Drives)

Date: 25 July, 2014

Time: 3 hours

Max Marks: 60

1.	a)	Explain the function of following Assembler directives: DB .CODE	6M
	b)	ORG Explain the function of the following flag bits of 8086: i. The auxiliary carry flag (AF) ii. Interrupt flag (IF)	6M
2.	a)	Explain the functions of the following pins of 8086: i. RESET ii. \overline{BHE} /S7 iii. \overline{LOCK}	6M
	b)	Explain the minimum mode of 8086 with block diagram.	6M
3.	a)	Explain the operation performed by 8086 when the following instructions are executed: i. DAS ii. LOOPNZ iii. PUSH & POP	6M
	b)	Differentiate between MACRO and a PROCEDURE.	6M
4.	a) b)	What do you mean by paging? Discuss the paging mechanism of 80386 processor. Differentiate between RISC and CISC processors.	8M 4M
5.	a) b)	Explain how 8255 is programmed, showing the internal command register content. Describe how ADC and DAC are interfaced to Microprocessor.	6M 6M
6.	a)	For what purpose, 8259 PIC is connected to microprocessors? With neat circuit diagram	6M
	b)	What is the necessity of serial communication interface? Explain command and status register formats in 8251.	6M
7.	a)	With a neat diagram, write the programming model of 8051. Also give the 128 bytes	6M
	b)	Explain the function of a Program Status Word (PSW) SFR, giving the content of the register.	6M

8.	a)	a) Explain the following inst i. SWAP A	Explain the following instructions of 8051 with example.	6M
			i. SWAP A	
		ii. DA A		
		iii. MOVC A, @A+PC		
		iv. XCHD A, @Ri		
	b)	Explain the function of IE and IP registers with their bit pattern.	6M	



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M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

ENERGY CONVERSION SYSTEMS

(Power Electronics and Electric Drives)

Date: 26 July, 2014

Time: 3 hours

Max Marks: 60

Answer any Five Questions. All Questions carry equal marks. All parts of the question must be answered in one place only.

1.	a) b)	Describe the principle of photo-voltaic energy conversion. What is superconductivity? Briefly explain the three important physical properties which govern the superconductivity of materials.	6M 6M
2.	a)	Explain the basic principle involved in MHD Power Generation.	5M
	b)	The internal resistance of an MHD duct is R_d = 2.5 m-Ohm. At a performance factor of K=0.5, what is the value of load resistance? If the generated voltage is 1500 V, what are the current and load power delivered? Calculate the efficiency of the generator.	7M
3.	a) b)	Explain the advantage of providing twisted blades in a wind turbine. Using suitable figures, explain power output variation of a wind power generator with wind speed variation.	6M 6M
4.	a) b)	Briefly explain different modes of generating electricity through tidal power. What are the major problems associated with the generating systems used in tidal power plants? Explain them briefly.	6M 6M
5.	a)	Explain the principle of ocean thermal energy conversion system.	6M
	b)	With relevant block diagrams explain the open cycle and closed cycle OTEC system.	6M
6.	a)	Draw the block diagram for generation of substitute natural gas from coal.	6M
	b)	Explain the principle of geothermal energy and its various applications.	6M
7.	a)	Explain various methods of energy storage in different energy conversion systems and compare them.	6M
	b)	With neat block Diagram, Explain the concept of combined cycle cogeneration.	6M
8.	a)	What are the advantages of fuel cells over other energy conversion systems?	6M
	b)	What are the measures taken to limit the effect of pollution of water bodies by the acidic effluents of coal based power plants?	6M

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M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

ADVANCED DATA COMMUNICATIONS

(Digital Electronics and Communications Systems)

Date: 28 July, 2014

1.

Time: 3 hours

Max Marks: 60

6M

Question Paper Code : B1401

Answer any Five Questions. All Questions carries equal marks. All parts of the question must be answered in one place only.

a) For BPSK Modulator with a carrier frequency of 60 MHz and an input bit rate of 10Mbps,

determine the maximum and minimum lower side frequency. Draw the output

	b)	 spectrum, determine the minimum Nyquist bandwidth and calculate the baud. Determine: Peak frequency Minimum bandwidth Baud For a binary FSK signal with a mark frequency of 49KHz, a space frequency of 51KHz and an input bit rate of 2kbps. 	6M
2.	a)	Find the DPSK (Differential Phase Shift Keying) Modulated signal for the input bit stream 101110001101. Using DPSK demodulator, reconstruct the signal from the modulated signal	6M
	b)	Consider 8-QAM transmitter for modulation, give the bandwidth considerations, truth table phasor diagram and constellation diagram for the above mentioned modulation concept.	6M
3.	a) b)	Discuss the advantages and disadvantages of bus, star and mesh topologies. Explain about the network interface Protocols Standards of data communication networks.	6M 6M
4.	a) b)	Describe two types of wide area networks. Explain the significance of DTE and DCE in data transmission.	6M 6M
5.	a)	Draw the NRZ-Unipolar, RZ- unipolar, NRZ-polar, RZ-polar and Manchester Line codes for the given bit stream 101110011	5M
	b)	Explain about statistical time division multiplexing.	7M
6.	a)	Determine the transmitted data stream for the following data stream G(x) and CRC generating polynomial $P(x)G(x) = x^7 + x^5 + x^4 + x^2 + x^1 + x^0P(x) = x^5 + x^4 + x^2 + x^0$	6M
	b)	Briefly describe the sliding window method of flow control.	6M
7.	a) b)	Explain IBM's Bisync Protocol. Draw structure of SDLC frame format. Explain in detail about SDLC control field.	6M 6M

a)	Explain the three phases required for circuit switched network.	6M
b)	Discuss about message switching and packet switching.	6M

8.



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M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

ADVANCED DIGITAL SIGNAL PROCESSING

(Common to Digital Electronics and Communications Systems &

Wireless and Mobile Communications)

Date: 22 July, 2014

Time: 3 hours

Max Marks: 60

1.	a) b)	A digital low pass filter is required to meet the following specifications: i. Monotonic stop band and pass band ii3.01dB at cutoff frequency of 0.5π rad/sec iii. Stop band attenuation of atleast 15dB at 0.75π rad/sec Design a FIR low pass filter with the following desired frequency specification: $Hd(e^{jw}) = \begin{cases} e^{-j^2w}; & w < \frac{\pi}{4} \\ 0; & \frac{\pi}{4} < w < \pi \end{cases}$	7M 5M
		Determine the filter coefficients $h(n)$ if rectangular window is used.	
2.	a)	Explain the technique for sampling rate conversion by a ratio factor I/D.	6M
	b)	Explain the process of decimation and derive the equation for spectrum of decimated sequence.	6M
3.	a)	With a block diagram explain FDM to TDM transmultiplexer.	6M
	b)	Discuss with block diagram oversampling of A/D converter and D/A converter.	6M
4.	a)	With necessary equation explain Levinson-durbin algorithm.	6M
	b)	Discuss any two properties of linear prediction filter.	6M
5.	a)	Write the relationships between the autocorrelation and the model parameters.	6M
	b)	Discuss Yule-Walker method for the AR model parameters.	6M
6.	Exp i. ii.	lain the following models for power spectrum estimation: MA model ARMA model	12M
7.	a)	Derive the solution of the weiner-hopf equation for linear transversal filter.	6M
	b)	Discuss multiple linear regression model.	6M
8.	Wit Kalr	h signal flow graph and relevant mathematical equations discuss the statement of the nann filtering problem.	12M





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M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

DIGITAL SYSTEMS DESIGN

(Digital Electronics and Communications Systems)

Date: 23 July, 2014

Time: 3 hours

Max Marks: 60

1.	a)	Using karnaugh maps, find a minimal sum-of –products expression for each of the following logic functions. Indicate the distinguished 1-Cells in each map. F = $\sum w,x,y,z (0,1,2,3,7,8,10,11,15)$	8M
	b)	$F = \sum w,x,y,z (1,2,4,7,8,11,13,14)$ Explain how timing and static hazards are minimized.	4M
2.	a)	Discuss the need of timing analysis of a combinational logic circuit and explain important timing constraints in designing a digital circuit.	6M
	b)	For a combinational circuit, explain following with the help of timing diagram.	6M
		 ii. Minimum delay iii. Maximum delay iv. Maximum operating frequency 	
3.	a)	Design 8-bit priority encoder using PAL20L8 PLD device.	6M
	b)	With the help of neat block diagram, explain working of iterative n-bit comparator.	6M
4.	a) b)	With necessary timing diagram of state machine and state table, explain steps for analyzing clocked synchronous state machines. Explain various timing issues in digital system design with the help of neat diagrams.	6M 6M
5.	a)	Explain setup time, hold time and clock skew in digital system design with the help of neat diagrams.	6M
	b)	What are the components of State machine chart? Explain with an example.	6M
6.	a)	What is state machine chart? Write the state machine chart for dice controller.	6M
	b)	Explain how state assignments are used for FPGA's.	6M
7.	a)	Discuss in detail about single stuck at fault model with example.	6M
	b)	With an example, explain fault detection and redundancy.	6M
8.	a)	Describe the algorithmic steps involved in D-algorithm.	6M
	b)	With an example, explain about the random testing method.	6M



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M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

CMOS VLSI DESIGN

(Digital Electronics and Communications Systems)

Date: 24 July, 2014

Time: 3 hours

Max Marks: 60

1.	a) b)	Define threshold voltage? Explain the dependence of V _T on other parameters. Draw the neat schematic diagram of small signal model for MOS Transistor in the active region and show that $V_{eff} = \sqrt{\frac{2ID}{\mu_n c_{ox}\left(\frac{W}{L}\right)}} \text{ and } g_m = \frac{2I_D}{V_{eff}}$	6M 6M
2.	a) b)	Explain and derive the necessary DC region equations of CMOS inverter. Explain: i. Propagation Delay ii. RC Model	8M 4M
3.	a) b)	With neat circuit diagram, explain the operation of PFET based 2:1 MUX. Explain the differences between pass transistor logic and transmission gate logic.	6M 6M
4.	a) b)	Design and explain the operation of CMOS 2 input NOR gate. Design a CMOS 1 bit full adder circuit.	6M 6M
5.	a) b)	With neat circuit diagram, explain the operation of NFET based Latching circuit. Design EX-OR gate using transmission gates.	6M 6M
6.	a)	Explain: i. Junction Reverse Leakage currents ii. Sub threshold leakage	6M
	b)	Draw the circuit diagram of C ² MOS latch circuit and Explain its operation.	6M
7.	a)	Write short notes on the following: i. Fan-in/Fan-out	6M
	b)	With a circuit diagram, explain the operation of AND-OR Domino logic gate.	6M
8.	a) b)	What is a dual Rail Logic network and explain in detail? With a neat circuit diagram, explain the operation of dynamic CVSL Circuit with Charge keeper.	6M 6M



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M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

CPLD AND FPGA ARCHITECTURES AND APPLICATIONS

(Digital Electronics and Communication Systems)

Date: 26 July, 2014

Time: 3 hours

Max Marks: 60

1.	a) b)	Explain advantages, history of FPGA and also discuss FPGA based system design briefly. With neat flowchart, explain design abstraction ladder for FPGAs.	6M 6M
2.	a) b)	With a neat block diagram, explain the operation of ALTERA APEX II logic element. Explain permanently programmed FPGA's.	8M 4M
3.	a) b)	Discuss the different logic elements to design FPGAs fabrics. How will you connect two logic elements in FPGA? Illustrate Rents rule.	6M 6M
4.	Exp i. ii. iii.	lain the following: Gate and wire delay Static timing analysis Critical path	12M
5.	a)	Explain: i. Technology independent logic optimization ii. Technology dependent logic optimization	8M
	b)	 Draw the schematics that represent the results of syntax directed translation of these statements: i. if (e) then x<=a b; else x<=a&-b; ii. if (e) then x<=a; else x<=a&-b; 	4M
6.	Des seq	ign a mealy FSM for a sequence detector which detects "001". The FSM output is '1' if the uence is detected otherwise '0'. Write the verilog code for the same.	12M
7.	a) b)	Design a BCD Counter using appropriate programmable logic element or device. Explain in detail about programmable sum -of -products array.	6M 6M
8.	a)	Draw the simplified block diagram of Xilinx XC4000 series CLB and explain the function briefly.	6M
	b)	Compare & list out the advantages of ALTERAs logic8000 with Xilinx XC4000.	6M



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M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

DSP PROCESSORS AND ARCHITECTURES

(Embedded Systems)

Date: 24 July, 2014

Time: 3 hours

Max Marks: 60

1.	a)	Compare Direct DFT & FFT in terms complex multiplications, additions and speed improvement factor for N=8	6M
	b)	Compute DFT for $x(n) = \{1, 1, 1, 1\}$ using radix-2 FFT algorithm.	6M
2.	a) b)	Show that for a A/D converter with 14 bits for signal representation SNR=83.04db. Calculate the dynamic range and precision of each of the following number Representation formats 64-bit ,Single –Precision, fixed –point format 128-bit, double –precision, fixed point format	6M 6M
3.	a) b)	Explain the purpose of Program sequencer. Draw the schematic diagram of saturation logic and explain the same.	6M 6M
4.	a) b)	Explain pipelined implementation of FIR filter Explain how interrupt is handled in DSP Processor	6M 6M
5.	a)	Identify the addressing mode of the source operand in each of the following instructions: i. ADD *AR2, A ii. ADD *AR2+,A iii. ADD *AR@+%,A iv. ADD#OFFh, A v. ADD ABCDh, A vi. ADD *AR@+OB,A	6M
	b)	A DSP has a circular buffer with the start and end addresses as 0200h and 020Fh respectively .What would be the new values of the address pointer of the buffer if, in the course of address computation , it gets updated to i) 0212h ii) 01FCh.	6M
6.	a)	Determine the value of each of the following 16-bit numbers represented using the given Q-notation: i. 4400h as a Q0 number ii. 4400h as Q15 number	6M

- iii. 4400h as a Q7 number
- b) Explain how a digital decimation filter can be implemented for a given decimation 6M factor.

7.	a)	Explain overflow and scaling.	4M
	b)	Implement an 8-point DIT – FFT on the TMS320C54XX with the help of program.	8M
8.	a) b)	Design a data memory system with address range 000800h-000FFFh for C5416 Processor use 2kx8 SRAM memory chips. Give the schematic of interface. How does DMA help in increasing the Processing speed of a DSP PROCESSOR?	6M 6M

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M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

SOFTWAE REQUIREMENT AND ESTIMATION

(Software Engineering)

Date: 23 July, 2014

Time: 3 hours

Max Marks: 60

Answer any Five Questions. All Questions carry equal marks. All parts of the question must be answered in one place only.

- a) An Automatic Teller Machine (ATM) is a computer based machine, connected to a network, that offers, as basic functions to users, access to bank account (balance, bank transfers) and retrieval of money. Assume that you are designing software for deploying on this machine. Identify any three functional and non-functional requirements for the same.
 - b) What is risk management? List any two common mistakes in risk management and 6M requirements for successful risk management.
- a) Using an elicitation method can help in producing a consistent and complete set of software requirements. However, there are numerous software requirement elicitation techniques available like Questionnaires, Task Analysis, Scenarios and Use cases. Suggest few evaluation criteria that may be useful in selecting an elicitation method.
 - b) Web applications have very high requirements for numerous quality attributes. 4M Identify any four critical software quality attributes that should be considered when developing such web apps.
 - c) The scholar John von Neumann once said. "There's no sense being exact about 3M something if you don't even know what you're talking about." In a world that is growing increasingly dependent on highly complex, computer-based systems, the importance of defining what your customer wants you to make before making it. In this direction suggest a method for exploring requirements quality before design.
- 3. a) Explain briefly state transition diagram with an example.
 - b) Consider a retail store called "XYZ COMPANY". It takes orders from its customers. The customers may be located at different parts of the country. Once the customer orders for product(s), they are checked against the inventory present in their warehouse. If present, an invoice is generated through a set of transactions. Finally, the products are packed and kept ready for delivery through shipment. The company provides free shipment for its customers.

Suppose XYZ COMPANY is interested in automating the complete ordering process, identify the classes required along with suitable members and represent them using class diagram.

4. a) List any six roles of a Requirements Analyst (RA).

6M

6M

b) The most common way to represent the links between requirements and other system 6M elements is in a requirements traceability matrix, also called a requirements trace matrix or a traceability table. Design a requirements traceability matrix for online examination and grading system.

5.	a) b)	Describe the features, advantages and drawbacks of Caliber RM tool. Assume that you are designing a requirements management tool, what aspects would you like to incorporate into your tool? Justify.	6M 6M
6.	a)	What is software estimation? Bring out its significance.	8M
	b)	List any four software estimation methods.	4M
7.	a)	What is software size estimation? List any six metrics for the same.	5M
	b)	Let's imagine a company which sells goods on the phone – if agents call the customers, customers call the agents, and so on – business operates successfully, but there comes a time for putting the whole in order. There occurs a need for developing a system able to control the whole stock, from orders to payments. The question of interset is to estimate how complex such system can be and try to predict how long it would take to develop it using Eurocional Points (EP).	7M
8.	a) b)	Describe Putnam estimation model. Write a brief note on University of Southern California's Constructive Cost Model estimation tool.	6M 6M



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M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

SOFTWARE PROCESS AND PROJECT MANAGEMENT

(Software Engineering)

Date: 24 July, 2014

Time: 3 hours

Max Marks: 60

1.	a)	Illustrate the different factors that makes software management is different from other engineering fields	6 M
	b)	Explain the basic principles of software process change.	6 M
2.	a) b)	What are the different process reference models? Write the significance of TSP. Give the differences between CMM and PCMM.	6 M 6 M
3.	a) b)	Based on what parameters software cost can be estimated? Explain. What are the long standing debates among developers and vendors of software cost estimation tools. Explain in detail.	6 M 6 M
4.	a) b)	Explain the term 'artifacts'. Discuss in detail about Management Artifacts. Which phase of the four phases of software life cycle is the most critical? Justify your statement.	6 M 6 M
5.	a) b)	How the concurrency among the stakeholders will be achieved using major milestones of the software process? Give the fundamental flaws in conventional work breakdown structures. Write the solution to overcome these flaws.	6 M 6 M
6.	a) b)	What is meant by "line of business organizations"? Write the role and responsibilities of these organization people. List the software development team activities and responsibilities.	6 M 6 M
7.	a) b)	How management indicators and quality indicators helps in achieving the project goals and the quality of software products? Discuss the role of degree of cooperation and coordination among stakeholders for defining a process. Support your views with clear explanation.	6 M 6 M
8.	a) b)	Discuss in detail about CSCI productivities and Quality factors involved in CCPDS-R. List and explain the critical approaches of modern process framework for resolving top ten risks.	6 M 6 M





(AUTONOMOUS)

M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

ADVANCED DATA STRUCTURES AND ALGORITHMS

(Embedded Systems)

Date: 28 July, 2014

Time: 3 hours

Max Marks: 60

Question Paper Code : B1601

Answer any Five Questions. All Questions carries equal marks. All parts of the question must be answered in one place only.

1.	 Assume that a linked list has Add(x) and Delete Odds() operations defined as: Add(x): Adds the element x to the end of the list. Delete Odds(): Delete the first , third, fifth etc., elements of the list. 												
	b)	Write the algorithm to implement the above operations. What do you mean by linear data structure? List the various techniques of implementing a linear data structure.	4M										
2.	a)	Discuss the asymptotic notations. How does one measure the efficiency of the	6M										
	b)	The time complexity of an algorithm can be measured using Aprioiri analysis or posteriori testing. Discuss these algorithms in detail?											
3.	a)	Explain how we can identify connected component of a graph by using: i. Depth First Search ii. Breadth First Search	8M										
	b)	What is threaded binary tree? Explain its advantages and applications.	4M										
4.	a)	Start with an empty AVL tree and perform insert operations using the following	6M										
	b)	Write a pseudo code for deleting a node from binary search tree. Consider all the possible cases.	6M										
5.	a)	For the following red-black trees (double links are red links) as shown in figure.1	8M										
		S: 2 B: 9											



- i. Perform Join(S; 8; B)
- ii. Split the tree S with respect to 3
- b) Write short notes on Hash function application and implementation techniques.

4M

10

Find a minimum-cost spanning tree using Kruskal's algorithm for the given graph in 6. a) figure.2.



- b) Write the pseudo code for sorting the elements of array in descending order using divide 6M and conquer technique.
- 7. a) What do you mean by dynamic programming? Explain the various steps of dynamic 6M programming in detail.
 - Given a set of cities and distance between every pair of cities as shown in figure.3, find 6M b) the shortest possible route that visits every city exactly once and returns to the starting point.



- 8. Present a backtracking algorithm for solving the N-Queen's problem. Draw the portion of 6M a) state space tree for the N-Queen's problem. 6M
 - b) Explain the branch and bound techniques and its applications.

6M



(AUTONOMOUS)

M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

MICROCONTROLLERS FOR EMBEDDED SYSTEM DESIGN

(Embedded Systems)

Date: 22 July, 2014

Time: 3 hours

Max Marks: 60

1.	a)	Explain the register banks available in 8051. Also explain the working of stack for PUSH, POP and CALL instructions	8M
	b)	Explain the data types and directive of 8051.	4M
2.	a)	Write an ALP to toggle all the bits of Port-1 by sending to it the values 55h and 0AAh. Put	8M
	b)	Write a program to generate a square wave of 25% duty cycle on pin P2.3.	4M
3.	a)	Describe 8051 memory structure and map internal memory structure with different addressing modes	6M
	b)	Write a program for the 8052 to put 55h into the upper RAM locations of 90 to 99h.	6M
4.	a)	Write an 8051 ALP to multiply the unsigned number in register R2 by the unsigned number in port-2 and put the result in external RAM location 20h and 21h	9M
	b)	 Find the content the content of the register A after the following code in each case: i. MOV A, #37h ANL A, #0CAh ii. MOV A, #37h ORL A, #0CAh iii. MOV A, #37h XRL A, #0CAh 	3М
5.	a)	Explain the following design metric: i. Time to Market ii. NRE and Unit Cost iii. Performance	9M
	b)	Briefly explain about application specific processors.	3M
6.	a)	Illustrate how program and data memory fetches can be overlapped in Harvard architecture	4M
	b)	Explain the various software design tools used for embedded system design.	8M
7.	a) b)	Explain the control of a DC motor using a PWM technique. Explain briefly the various functions of UART.	8M 4M
8.	a)	Explain memory hierarchy used in embedded system and what are the different types of memories used in embedded system design	6M
	b)	Explain RAM internals and Memory cell internals for i. SRAM ii. DRAM	6M

Hall	Tick	et No:]		Quest	tion Pa	iper Co	ode:	B1701
	VARDHAMAN COLLEGE OF ENGINEERING (AUTONOMOUS) M. Tech I Semester Supplementary Examinations July - 2014																	
	(Regulations: VCE-R11)																	
	APPLIED MATHEMATICS																	
	(Engineering Design)																	
Date: 28 July, 2014 Time: 3 hours Max Marks: 60															rks: 60			
	Answer any Five Questions. All Questions carries equal marks. All parts of the question must be answered in one place only.																	
_																		614
1.	a)	Explain four sid	i absoli Inifican	ite ar it digi	nd r∈ ts ar	elativ nd fi	ve er nd it	rors s ah	s Wit Nsoli	th ex ute a	am nd r	ple. Evaluate	e the s	sum S =	= √3 + √	5 + √7	to	UIVI
	b)	State c	onserva	ation	laws	s em	ploy	ed i	n ar	ny tw	vo n	najor areas of	f engi	neerinę	g with e	exampl	es.	6M
2.	a)	Use bis (correc	ection t up to	meth 3 deo	iod t cima	o fir I pla	nd a aces)	real	roo	t of	the	equation <i>x</i> lo	og ₁₀ x	= 1.2 b	etween	ı 2 and	3	6M

- b) Use Regula Falsi method to find a non-zero real root of the equation 6M $\sin x \cosh x + 1 = 0$ (correct to 3 decimal places).
- 3. a) Find the root of the equation $x^3 5x + 1 = 0$ which lies between 0 and 1 using 6M Muller's method.
 - b) Perform two iterations of the Bairstow method to extract a quadratic factor 6M $x^2 + px + q$ from the polynomial $P_3(x) = x^3 + x^2 x + 2 = 0$. Use the initial approximation $p_0 = -0.9$, $q_0 = 0.9$.
- a) The velocity v (km/min) of a moped which starts from rest, is given at fixed intervals of time t (min) as follows. Estimate the distance covered in 18 minutes using Simpson's rule.

t	2	4	6	8	10	12	14	16	18
V	10	18	25	29	32	20	11	5	2

b) Calculate the first and second derivatives of the function tabulated below at the point 6M x=1.0

x	1.0	1.2	1.4	1.6	1.8	2.0	2.2
y	2.7183	3.3201	4.0552	4.9530	6.0496	7.3891	9.0250

::2::

5.	a)	Find the inverse of the matrix using Gauss-Jordan method:	6M
		$A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$	
	b)	Solve the following system of linear equations by using cholesky method.	6M
		$ \begin{pmatrix} 1 & 2 & 3 \\ 2 & 8 & 22 \\ 3 & 22 & 82 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 5 \\ 6 \\ -10 \end{pmatrix} $	
6.	a)	Find all the eigenvalues of the matrix $A = \begin{bmatrix} 4 & 3 \\ 1 & 2 \end{bmatrix}$ using the Rutishauser method.	6M
		$\begin{bmatrix} 1 & 2 & 4 \end{bmatrix}$	

b) Transform the matrix
$$A = \begin{bmatrix} 2 & 1 & 2 \\ 2 & 1 & 2 \\ 4 & 2 & 1 \end{bmatrix}$$
 to tridiagonal from by Givens method. 6M

7. a) The following table gives three ingredients in the diet together with the amount of certain nutrients supplied by 100 mg of each ingredient. If possible find some combination of fruits to provide the exact amount of Vitamin C, Calcium and Magnesium supplied by the diet in one day.

Nutrient	Amount nutrients per unit	(mg) of S of food		Total nutrients required
	Banana	Apple	Orange	(mg)
Vitamin C	10	20	20	100
Calcium	50	40	10	300
Magnesium	30	10	40	200

- b) Define Linear transformation. Obtain the matrix T that transforms (2,5) to (1,1) and (1,3) 6M to (0,2).
- 8. a) Find the best line b = C + Dt to fit b = 4, 2, -1, 0, 0 at times t = -2, -1, 0, 1, 2. 6M
 - b) Apply Gram Schmidt process to a = (1, 2, -2), b = (1, -1, 4) and c = (-2, 2, 1) and write 6M the result in the form A=QR.

Hall Ticket No: Question Paper Code : B170 VARDHAMAN COLLEGE OF ENGINEERING (AUTONOMOUS) (AUTONOMOUS) M. Tech I Semester Supplementary Examinations July - 2014 (Regulations: VCE-R11) ADVANCED MACHANICS OF SOLIDS (Engineering Design) Date: 22 July, 2014 Time: 3 hours Max Marks: 60		Answ All p	ver any arts of	Five Qu the que	estio stior	ons. A n mus	ll Qu t be a	lestions carries e answered in one	equal marks. place only.							
Hall Ticket No: Question Paper Code : B170 VARDHAMAN COLLEGE OF ENGINEERING (AUTONOMOUS) N. Tech I Semester Supplementary Examinations July - 2014 (Regulations: VCE-R11) ADVANCED MACHANICS OF SOLIDS (Engineering Design)	Date: 22 July, 20)14				Time	: 3 h	ours		Max Marks: 60						
Hall Ticket No: Question Paper Code : B170 VARDHAMAN COLLEGE OF ENGINEERING (AUTONOMOUS) N. Tech I Semester Supplementary Examinations July - 2014 (Regulations: VCE-R11) ADVANCED MACHANICS OF SOLIDS					(En	ginee	ring	Design)								
Hall Ticket No: Question Paper Code : B170 VARDHAMAN COLLEGE OF ENGINEERING (AUTONOMOUS) M. Tech I Semester Supplementary Examinations July - 2014 (Regulations: VCE-R11)			Α	DVAN	CED	MAC	HAI	VICS OF SOLID	S							
Hall Ticket No: Question Paper Code : B170 VARDHAMAN COLLEGE OF ENGINEERING (AUTONOMOUS) M. Tech I Semester Supplementary Examinations July - 2014					(Reg	ulatic	ons: \	/CE-R11)								
Hall Ticket No: Question Paper Code : B170 VARDHAMAN COLLEGE OF ENGINEERING (AUTONOMOUS)		Μ.	Tech I S	emeste	r Sup	plem	entai	ry Examinations.	July - 2014							
Hall Ticket No: Question Paper Code : B170. VARDHAMAN COLLEGE OF ENGINEERING	VARDH.	(AUTONOMOUS)														
Hall Ticket No: Question Paper Code : B170.	STATE OF THE		/ARDł	HAMA	N CO	OLLE	GE	OF ENGINEI	ERING							
	Hall Ticket No:								Question Pa	per Code : B1702						

- 1. Define the term shear center and enumerate the procedure for calculating the shear center 12M for Unsymmetrical sections.
- 2. Plates are welded together to form the 120mm by 80mm by 10mm angle section beam as shown in the Fig.1. The beam is subjected to concentrated load of 4Kn(P) as shown. The load P lies in the plane making an angle $\Phi = 2\pi/3$ with the x-z plane. Load P passes through shear center C which is located at the intersection of the two legs of the angle section. Determine the max tensile and compressive bending stresses at the section of the beam where the load is applied. Solve the problem using the load- stress relations derived for non symmetrical bending.



3. A glued laminated beam is used in a roof system. The beam has a simple span of 15m and 12M the middle half of the beam is curved with a mean radius of 10m. The beam depth and width are both constant: d = 0.800m and b = 0.130m. Dead load is 2400N/m and snow load is 4800N/m. The geometry of the beam and the assumed loading are shown in Fig.2. Determine the max circumferential stress and radial stress in the beam. Compare the maximum circumferential stress to that obtained from the straight beam flexure formula.



4. A hollow thin wall torsion member has two compartments with cross sectional dimensions 12M as shown. The material is an aluminum alloy for which G = 26GPa. Determine the torque and the unit angle of twist if the max shear stress at locations away from the stress concentration is 40 MPa.



- 5. Derive an equation for bending of a beam by uniform loading. 12M
- 6. Derive an equation for stress distribution in a rotating circular disc. 12M
- 7. An Aluminum alloy I beam (depth = 100mm, $I_x = 2.45 \times 10^6$ mm⁴ and E = 72 GPa) has a length L 12M = 6.8m and is supported by seven identical springs (K = 110N/mm) spaced at a distance I = 1.10m center to center along the beam. A load of P = 12kN is applied at the center of the beam over one of the springs. Determine the load carried by each spring, the deflection of the beam under the load, the max bending moment and the max bending stress in the beam.

8.	a)	State the assumptions on which solution for contact stresses is based	6M
	b)	Derive an equation for deflection of bodies in point contact	6M

Hall 1	Fick e	t No: Question Paper Code :	B1703												
	VARDHAMAN COLLEGE OF ENGINEERING (AUTONOMOUS) M. Tech I Semester Supplementary Examinations July - 2014 (Regulations: VCE-R11) ADVANCED MECHANISMS														
(Engineering Design) Date: 23 July, 2014 Time: 3 hours Max Marks: 6															
Date	. 200	Answer any Five Questions. All Questions carry equal marks.	K3. UU												
	All parts of the question must be answered in one place only.														
1.	a) b)	Differentiate between spherical mechanisms and spatial mechanisms with example. Give the symbolic illustration of revolute and prismatic joints of a Robot.	6M 6M												
2.	a) b)	Define the terms inflection points and inflection circle related to kinematics of motion. Show the Bobillier Construction for finding the inflection point J_A when I, A and O_A are known on the ray IA. Assume the dimensions suitably where ever needed.	4M 8M												
3.	a) b)	State and prove Freudenstein's collineation axis theorem. Discuss about polode curvature in the four bar mechanism.	6M 6M												
4.	a) b)	Explain two-position synthesis of centered slider crank – mechanism. Explain in detail how Burmester's curve will be drawn for a 4-bar mechanism.	3M 9M												
5.	Syn [:] the	thesize a function generator to solve the equation $y = x^{0.6}$, in the interval $1 \le x \le 3$, with range is divided into six intervals. Use Overlay method.	12M												
6.	Des follo i. ii. Tak	ign and draw a four link mechanism to coordinate 3 positions of input and output links as bws: $\theta_1 = 20^0, \theta_2 = 35^0, \theta_3 = 50^0$ $\phi_1 = 35^0, \phi_2 = 45^0, \phi_3 = 60^0$ e d=1. Use Freudenstein's equation.	12M												
7.	a) b)	Assign coordinate frames based on D-H representation for the SCARA type robot. Established link co-ordinates system for a PUMA robot with neat sketch.	4M 8M												
8.	a) b)	Explain similarity analysis in manipulator kinematics. Explain the formulation of Jacobian for planar manipulator.	6M 6M												



(AUTONOMOUS)

M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

FINITE ELEMENT METHODS

(Engineering Design)

Date: 24 July, 2014

Time: 3 hours

Max Marks: 60

- 1. a) What are the advantages of variational formulation over differential equations 6M formulation? Compare Variational Methods and Weighted residual methods for carrying out engineering analysis.
 - b) Determine the maximum deflection of a simply supported beam subjected to UDL 6M using an approximate analytical method which uses the principle of minimum potential energy.
- a) A Tapered bar of circular cross section from 100 mm to 85 mm is subjected to a tensile 8M load of 1KN. E= 2.1X10⁵ MPa. If the length of the member is 950 mm, determine the change in length and stress in this member using a minimum of two elements. Use penalty method.
 - b) Derive interpolation functions for a 2nd order bar element and plot their variation over 4M its length.
- a) A planar truss is in the form of a right angled triangle with one corner on the origin of 10M X-Y Cartesian coordinate system. One member located on the X axis measures 4 m and another member located on the Y axis measures 3 m. The left end of the member which is on the x axis is fixed. The right end of this member has a roller support to constrain the displacement in the y direction and a load of M KN is applied in the positive X direction at this node. If this node experiences a displacement of 0.1 mm along the positive X axis, determine "M" and the stresses in the members. Area of each member = 2026.83 mm² and E= 2.1X10⁵ MPa. Find the support reactions
 - b) Derive the Transformation matrix for a truss element having 2 dof at each node. 2M
- 4. a) Derive Hermite shape functions for a 1-D beam element and plot their variation over 8M its length.
 - b) What are C⁰, C¹ and C² continuous shape functions? What are the differences between 4M truss elements and beam elements?

Determine the strains experienced by a CST element (Assume Plane strain condition). There 12M is a node at each corner of the element. Edge 23 is fixed. A force of 10KN is applied at node 1 in the +ve X direction. Poisson's ratio is 0.3. E= 2.1X10⁵, thickness=0.3. All dimensions are in mm.



- 6. a) Integrate the following function numerically using Gaussian quadrature technique. 6M $I = \left[\frac{x^2}{y^{-1}} + 23x\right] 2 \le x \le 3; 0 \le y \le 1$
 - b) With examples explain iso, sub and super parametric elements, clearly indicate their 6M applications.
- a) Evaluate the lowest Eigen value and the corresponding Eigen mode for the cantilever 7M beam of length 600 mm, area 240 mm², density 7.84g/cc and modulus of elasticity 200 GPa.
 - b) What are the 3 basic categories of Eigen value Eigen vector evaluation procedure? 5M
- 8. a) "The assumed displacement function in the FEM need not satisfy the BC's. But they 6M must satisfy the requirements for convergence" Say Yes or No. Justify your answer
 - b) Differentiate between h refinement and p refinement of FE meshes. Clearly 6M indicating their differences while meshing curved surfaces.

Hall	Ticke	t No:					cket No: Question Pap								n Pap	er Code : B1801		
Date	e: 28 J	VARDHA	M.	/AR Tech AI	RDF TISC DV#	HAN eme ANC	//AI ester CED	VC Su (Re EN (Stru	OL AUT pple gula IGIN uctu Tin	LEG ONO ment tions IEER ral Er ne: 3	E O MOU ary I : VCI ING ngine hou	DFE US) Exai E-R' i M eeri eeri	ENG minat 11) IATHE ing)	INEEF ions Ju	RING 1y - 201 ICS	4	Max Ma	rks: 60
			Answ All p	ver a Parts	ny I of t	Five the o	Que que	esti stio	ons. n mi	All C ust be	Ques e ans	tior swe	ns car ered in	ries eq 1 one p	ual mai lace on	rks. Ily.		
1.	a)	Solve t	the foll	lowin	ıg sy	vster	n of	line	ar eq 3	Juatio $x_1 + 3$ $x_1 + 3$	ns by $x_2 - 3x_2 + 3x_2 + 2x_3$	y LU - x ₃ + 5x	U decor $r_{3} = 2$ $r_{3} = -3$	npositic 3	on meth	od.		6M
	b)	Deterr	nine th	ne inv	/ers	e of	the	mat	rix [$5x_1 + 1 - 1$ -1 4 2 6	$2x_2$ 1 2 6 29	_ 3,	$x_3 = 0$ y Gaus	s-Jorda	n metho	od.		6M
2.	a) -	Fransfor	m the	matri	ix A		1 2 2 1 2 2	2 2 2 2 2 1	2 2 to 1	tridia	igoni	al fr	om by	Givens	methoo	J.		OIVI
	b) (Using the	e Jacol ix A =	bi me [2 1 1	etho 1 1 0	d fir 1 0 1	nd al	ll th	e eig	en va	lues	and	d the c	orrespc	onding e	igenv	ectors of	6M

3. a) Construct Lagrange's interpolation polynomial for the following data and hence find 6M f(9)

x	4	6	8
У	1	3	8

6M

x	0	1	2	3		
f(x)	1	2	33	244		

Fit quadratic splines with M = f''(0) = 0. Hence, find an estimate of f(2.5).

b)

Given the data

4. a) The displacement of an instrument subjected to a random vibration test at different 6M instants of time, is found to be as follows:

Station(i)	1	2	3	4	5	6
Time t_i (sec)	0.05	0.10	0.20	0.25	0.30	0.35
Displacement $y_i(inch)$	0.144	0.172	0.213	0.296	0.076	0.085

Find the velocity $\left(\frac{dy}{dt}\right)$, acceleration $\left(\frac{d^2y}{dt^2}\right)$ and jerk $\left(\frac{d^3y}{dt^3}\right)$ at t = 0.05 and 0.20, using

the suitable finite difference formulas, with a step size $\Delta t = 0.05 \text{ sec}$.

b) Compute f'(3) from the following table using the formula $f'(x_1) = \frac{f(x_2) - f(x_0)}{2h}$ and 6M perform the Richardson extrapolation.

x	-1	1	2	3	4	5	7
f(x)	1	1	16	81	256	625	2401

5. a) Find the Jacobian matrix for the system of equations $f_1(x, y) = x^2 - y^2 + 2x = 0$ at the point (1,1) $f_2(x, y) = x^2 + y^2 + y = 0$

b) Find
$$\frac{dy}{dx}$$
 and $\frac{d^2y}{dx^2}$ at $x = 1.9$ from the following table:

<i>x</i> :	1	1.2	1.4	1.6	1.8	2.0
y :	0.00	0.128	0.544	1.296	2.432	4.00

6. a) A differentiation rule of the form

$$hf'(x) = \alpha_0 f(x_0) + \alpha_1 f(x_1) + \alpha_2 f(x_2) + \alpha_3 f(x_3), \quad (x_k = x_0 + \text{kh})$$

is given. Determine the values of $\alpha_0, \alpha_1, \alpha_2$ and α_3 so that the rule is exact for a polynomial of degree 4.

- b) Evaluate the mixed partial derivatives $\frac{\partial^3 f}{\partial x \partial y^2}$ of the function $f(x, y) = x^3 y^3$ using 6M central differences at x = 1 and y = 1 with a step size $\Delta x = \Delta y = 0.1$
- The velocity v (km/min) of a moped which starts from rest, is given at fixed intervals of time t (min) as follows. Estimate the distance covered in 18 minutes using Simpson's rule.

t	2	4	6	8	10	12	14	16	18
V	10	18	25	29	32	20	11	5	2

b) Evaluate the integral $I = \int_{y=1}^{2} \int_{x=1}^{2} \frac{dxdy}{x+y}$ using the trapezoidal rule with h=k=0.5. 6M

Improve the estimate using Romberg integration.

- 8. a) Find by Taylor's series method the value of y at x = 0.1 and x = 0.2 to five places of 6M decimals from $\frac{dy}{dx} = x^2 y 1$, y(0) = 1. Consider up to 4th degree terms.
 - b) By using the Modified Euler's method, solve the problem $y' = x^2 + y$, y(0) = 1 at 6M x = 0.02.

6M

6M

6M



(AUTONOMOUS)

M. Tech I Semester Supplementary Examinations July - 2014

(Regulations: VCE-R11)

THEORY OF ELASTICITY AND PLASTICITY

(Structural Engineering)

Date: 22 July, 2014

Time: 3 hours

Max Marks: 60

Answer any Five Questions. All Questions carries equal marks. All parts of the question must be answered in one place only.

- 1. a) The state of stress in MPa at a point is given by $\sigma_x = -120$, $\sigma_y = 140$, $\sigma_z = 66$, 6M $\tau_{yz} = -65$, $\tau_{zx} = 25$. Determine three principle stresses and direction associated with the three principle stresses.
 - b) Find the components of linear strain and component of rotation for the given 6M displacement components : $Ux = C_x(y + z)^2$, $Uy = C_y(z + x)^2$, $Uz = C_z(x + y)^2$ where C is a constant.
- 2. a) Prove that the following are Airy's stress function and examine the stress distribution 6M represented by them.

 $\Phi = Ax^{2} + By^{2}$ $\Phi = A(x^{4} - 3x^{2}y^{2})$ $\Phi = Ax^{3}$

b) The state of stress at a particular point relative to the xyz coordinates system is given by the stress matrix given below. Determine the normal stress, magnitude and direction of shear stress on a surface intersecting a point and parallel to the plane given by the equation 2x - y + 3x = 9

 $\begin{bmatrix} 15 & 10 & 10 \\ 19 & 10 & 10 \\ -10 & 0 & 40 \end{bmatrix}$

- 3. a) Determine the stress components from the following stress functions and calculate 6M their values when $\alpha = 20^{\circ}$ and $\alpha = 30^{\circ}$. $\Phi = Cr^{2}(\alpha - \theta) + r^{2}\sin\theta\cos\theta - r^{2}\cos^{2}\theta\tan\theta$.
 - b) Write basic equation of equilibrium of plane stress and plane strain in polar 6M coordinates.
- 4. Determine the normal stress, circumferential stress and shear stress for a stress function 12M $\Phi = A \log r + Br^2 \log r + Cr^2 + D.$
- 5. a) Explain and illustrate the principle of superposition and uniqueness theorem.
 b) Write and explain equations of equilibrium in terms of displacements.
 6M
- 6. Prove that $\nabla^2 = -2G\theta$, Poisson's equation for torsion of prismatic bar of non circular cross 12M section.

- 7. a) Derive the equation of shear stress $\tau_{xy} = 4/3$ (P/A) along with the horizontal dia. of the 6M
 - b) between the bar subjected to bending using elementary beam theory.
 b) Determine the max. stress in the cantilever beam of 5 m span subjected to a load of 1 kN at the free end of a cross section of (80 x 100) mm at an angle of 30^o to the vertical. 6M

8.	a)	Explain Elastic- Perfectly plastic	material	6M
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b) Explain Elastic linear strain hardening material with the stress – strain diagram for the 6M material.

Hall Ticket No:							Que	estion Pap	er Code : B1803
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	171.	IECH I S	emeste	(Regu	lation	nai 1s: 1	/CE-R11)	- 2014	
			FIN	TE EI	LEME	NT	ANALYSIS		
				(Struc	tural I	Engi	ineering)		
Date: 23 July, 20)14			٦	lime:	3 h	ours		Max Marks: 60
	Ansv	ver any	Five Qu	iestio	ns. Al	I Qi	uestions carry equal	marks.	
	All p	arts of t	he que	stion	must l	be a	inswered in one pla	ce only.	

- 1. A simply supported beam carries a point load P at the two quarter span points. Calculate 12M the bending moment and shear force which shall be the maximum by Raleigh-Ritz method and hence compare the exact solution.
- 2. A displacement field $U = 4 + 6x^3 + 2xy^2$, $V = xy^2 2y^3$ is imposed on a triangular 12M element whose nodes are (1, 1), (6, 1), (4, 8).
 - i. Write the expressions for $\varepsilon_x, \varepsilon_y$
 - ii. If E = 200 GPA, find σ_x, σ_y and ξ_{xy} assuming plane strain condition
- 3. A bar of uniform cross section is shown in Fig 1. Determine the elongation and reaction at 12M the fixed end for the given loading condition.



4. For the four sided element shown in Fig.2, determine the Jacobian matrix and the strain 12M displacement matrix.



- 5. Derive the stiffness matrix for a four noded square element. 12M
- 6. Derive the shape function for a six noded polygon element in natural coordinates. 12M
- 7. An open ended cone of height 200 mm, slant height 300mm and outer diameter 200mm 12M and wall thickness 10mm is subjected to an internal pressure of 2Mpa. Identify the problem and explain in detail how the problem can be solved by finite element method.
- 8. Using 2x2 rule, evaluate $\iint_{A} (3x+2x^2+xy) dxdy$ over the given area shown in Fig.3 by 12M Gaussian Quadrature method.

