

Invigilator's Signature :

CS/B.Tech (BME)/SEM-7/BME-703/2009-10 2009 POWER AND CONTROL SYSTEM

Time Allotted : 3 Hours

Full Marks : 70

The figures in the margin indicate full marks. Candidates are required to give their answers in their own words as far as practicable.

GROUP – A (Multiple Choice Type Questions)

- 1. Choose the correct alternatives for the following : $10 \times 1 = 10$
 - i) The transfer function is defined for
 - a) linear and time variant system
 - b) linear and time invariant system
 - c) non-linear and time variant system
 - d) non-linear and time invariant system.
 - ii) An error detector is a control system that
 - a) detects one error and signals out an alarm
 - b) detects the error of the system only
 - c) produces an error signal of difference between the actual output and the desired value of the output
 - d) none of these.

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CS/B.Tech (BME)/SEM-7/BME-703/ 2009-10 Ulech viii) A phase controlled converter supplies a highly inductive load. It behaves as naturally commutated inverter when firing angle (α) is a) $\alpha > 90^{\circ}$ b) $\alpha < 90^{\circ}$ c) $\alpha = 90^{\circ}$ d) $\alpha = 45^{\circ}$.

A single phase full converter with free wheeling diode, ix) supplies a high inductive load. The free wheeling diode conducts for (assuming continuous load current)

a) b) α $\pi - \alpha$ c) d) β $\pi + \alpha$.

The overall gain of the system show below is given by X)



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a)



GROUP – B (**Short Answer Type Questions**) Answer any *three* of the following.

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3 + 2

- 2. What are the main functions of a freewheeling diode ?
- 3. What is inverter ? Write down the classification of different types of inverters.
- 4. Find the overall T.F. using Manson's gain formula for the signal flow graph shown below :

- 5. Find the time response of 1st order control system subjected to unit ramp input function.
- 6. The characteristic equation for certain feedback control system is given below. Determine the range of values of K (K > 0) for which the system is stable.

 $S^4 + S^3 + S^2 + S + K = 0.$

- 7. a) What are the conditions for successful switching (turnon) of an SCR ?
 - b) What is the turn-off time of thyristors ?

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- 8. Sketch the nature of root locus of the system with loop transfer function $G(s)H(s) = \frac{k(s+2)}{s(s+5)(s+7)}$ as *k* varied from zero to infinity.
- 9. a) Define the terms 'gain margin' & 'phase margin'.
 - b) A unit feedback control system has open loop transfer function $G(s) = \frac{200(s+5)}{s(s+5)(s+20)}$. Sketch the Bode plot & show gain margin, phase margin, gain crossover frequency & phase crossover frequency. 4+7+4
- 10. a) Find the system equation of the mechanical system shown below. Also find the force-voltage (f-v) and force-current (f-i) analogy.

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block diagram reduction technique.



10 + 5

- Why are snubber circuits used ? Explain the circuit 11. a) diagram.
 - Why an RC triggering circuit cannot be used for an SCR b) for α close to 180°.
 - c) What are the drawbacks of a resistance-triggering circuit?
 - What are the advantages of a sharp gate signal for an d) SCR? 6 + 5 + 2 + 2
- What are the merits of *d.c-d.c* converters ? 12. a)
 - What is a first and second quadrant converter ? Explain b) with circuit diagram.
 - What is the principle of operation of a step-up c) converter ? Explain with circuit diagram. 2 + 7 + 6

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