



(Karunya Institute of Technology and Sciences) (Declared as Deemed to be University under Sec.3 of the UGC Act, 1956)

# End Semester Examination (Model Question Paper – April 2014)

Subject Title: INDUSTRIAL ROBOTICS Subject Code: 09ME248

Time: 3 hours **Maximum Marks: 100** 

### **Answer ALL questions**

## $\underline{PART} - A (10 \times 1 = 10 \text{ MARKS})$

- 1. Define Robot as per RIA?
- 2. What are the robot configurations.
- 3. What are the main characteristics of a robot?
- 4. Define work volume.
- 5. Draw the graphical representation of Rotational joint in DH notation.
- 6. Write the homogeneous rotational matrix about X- axis
- 7. Name few Robot programming Languages.
- 8. Define Yaw, Pitch and Roll?
- 9. What are the components of Machine Vision?
- 10. Write few non-manufacturing applications of robots.

## PART - B (5 x 3 = 15 MARKS)

- 11. Write various definitions of Robots.
- 12. What are the various types of end-effectors?
- 13. What are the functions of machine vision?
- 14. Write briefly about robot languages
- 15. Explain the application of robot in loading and unloading.

### $PART - C (5 \times 15 = 75 MARKS)$

16. What are the laws of Robot and explain the origin of robotics.

#### (OR)

- 17. Explain the various robot configurations with neat sketches.
- 18. What is DH convention for selecting frames of reference in robotic application, explain.

#### (OR)

- 19. Discuss the following robot grippers with neat diagrams:
  - a) Mechanical Grippers
  - b) Magnetic Gripper
  - c) Scoops and Ladles
- 20. Explain two Proximity sensors mostly used in robots.

(OR)

- 21. What is Robot Vision and explain in detail.
- 22. Explain various Robot programming methods.

(OR)

- 23. Define AI and explain the goals of AI.
- 24. Explain the application of robots in loading\unloading.

(OR)

25. Explain the application of robots in welding.