CODE: ES

M.Tech. Common Entrance Test, PGCET - 2010

Electrical Sciences (EE/EC/TC/BM/ML/IT)

Time: 2 Hours

Max. Marks: 100

Read the following instructions before answering the test

- i) Write / darken the particulars of your identity, Test Seat Number and affix your signature on the OMR Response Sheet before the start of the test.
- ii) All Questions have multiple choices of answers, of which only one is correct.
- iii) Mark the correct answer by completely darkening only one oval against the Question number using Black Ink Ball Point pen only.
- iv) There will be no negative evaluation with regard to wrong answers. Marks will not be awarded if multiple answers are given.
- v) Do not make any stray mark on the OMR Response sheet. For rough work, use blank page on the Question paper.
- vi) Taking the Question paper out of the test hall is permitted only after the full duration of the test.
- vii) Use of only non-programmable calculator is permitted.
- viii) START ANSWERING ONLY AT THE SPECIFIED TIME WHEN THE INVIGILATOR GIVES INSTRUCTIONS.

MARKS DISTRIBUTION

six.	PART – A
Section - I	30 Questions

Section - II

30 Questions: $30 \times 1 = 30 \text{ Marks}$ 15 Questions: $15 \times 2 = 30 \text{ Marks}$

PART - B

Section – I 20 Questions : $20 \times 1 = 20 \text{ Marks}$ Section – II 10 Questions : $10 \times 2 = 20 \text{ Marks}$ Total = 100 Marks

(Common to EE/EC/TC/BM/ML/IT)

SECTION - I of PART - A

. Each question carries One Mark

 $30 \times 1 = 30 \text{ Marks}$

1. The Transfer function of a system with time delay expressed by the differential equation $\frac{d}{dt}y(t) + y(t) = u(t - T)$ is given by

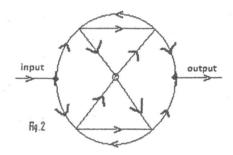
a.
$$\frac{e^{-sT}}{s+1}$$

b.
$$\frac{(s-1)}{(s+1)}$$

a.
$$\frac{e^{-sT}}{s+1}$$
 b. $\frac{(s-1)}{(s+1)}$ c. $\frac{-se^{-sT}}{(s+1)}$ d. $\frac{(s+1)}{(s-1)}$

$$d. \frac{(s+1)}{(s-1)}$$

2. The signal flow graph shown in Fig.2 has M number of forward paths and P number of individual loops then



a.
$$M = 6$$
, $P = 6$ b. $M = 6$, $P = 4$

b.
$$M = 6$$
, $P = 4$

c.
$$M = 4$$
, $P = 0$

c.
$$M = 4$$
, $P = 6$ d. $M = 4$, $P = 4$

- Gain margin for a system with $GH(j\omega) = \frac{1}{(j\omega + 1)^3}$ is 3.
 - a.2

- b. 4
- c. 6
- d. 8

- The rise time T_r for $c(t) = 1 e^{-t}$ is given by 4.
 - a. 1.198
- b. 2.198
- c. 2.298
- d. 3.298
- The h-parameter for a two-port network are $[h] = \begin{bmatrix} 9\Omega & -2 \\ 20 & 0.2s \end{bmatrix}$. The new h-parameter that results if 1Ω resistor is connected in series with the input is

a.
$$\begin{bmatrix} 10\Omega & -2 \\ 20 & 0.2s \end{bmatrix}$$

b.
$$\begin{bmatrix} 10\Omega & -3 \\ 2 & 0.2s \end{bmatrix}$$

c.
$$\begin{bmatrix} 10\Omega & -2 \\ 21 & 0.2s \end{bmatrix}$$

a.
$$\begin{bmatrix} 10\Omega & -2 \\ 20 & 0.2s \end{bmatrix}$$
 b. $\begin{bmatrix} 10\Omega & -3 \\ 2 & 0.2s \end{bmatrix}$ c. $\begin{bmatrix} 10\Omega & -2 \\ 21 & 0.2s \end{bmatrix}$ d. $\begin{bmatrix} 10\Omega & -2 \\ 21 & 0.3s \end{bmatrix}$

The value of H for a solid cylindrical conductor of radius 'a' with the current 'I' being uniformly distributed over the cross section is

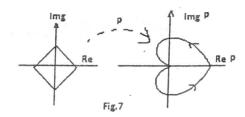
a.
$$\left(\frac{1}{2\pi r}\right)a_{\varphi}$$
 b. $\left(\frac{1}{4\pi r}\right)a_{\varphi}$ c. $\left(\frac{2}{\pi r}\right)a_{\varphi}$ d. $\left(\frac{1}{\pi r}\right)a_{\varphi}$

b.
$$\left(\frac{1}{4\pi r}\right)a_{\varphi}$$

c.
$$\left(\frac{2}{\pi r}\right)a_{\varphi}$$

d.
$$\left(\frac{1}{\pi r}\right)a_{q}$$

7. The number of poles P_o enclosed by the complex-plane contour of Fig.7 with $Z_o = 0$ is equal to

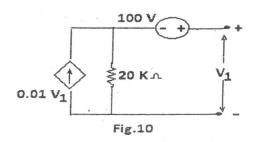


a. 0

- b. -1
- c. 1
- d. 2

- A soft error in DRAM 8.
 - a. cannot be recovered
 - c. can be recovered by reprogramming
- b. cannot be corrected
- d. none of the above

- 9. Flip flop is an
 - a. active device
- b. passive device
- c. inactive device d. none of the above
- 10. The Thevenin's equivalent for the network in Fig.10



a. -502.5mV, -100.5 Ω

b. - 502.5 mV, 100.5Ω

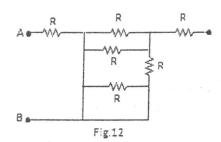
c. 502.5 mV, -100.5Ω

- d. 100.5 mV, 502.5Ω
- 11. The loaded voltage gain of an amplifier is always
 - a. equal to no-load gain

b. more than no-load gain

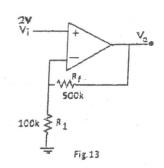
c. less than no-load gain

- d. none of the above
- The resistance R_{AB} at the terminals AB in Fig.12 if $R = 1k\Omega$, is given by



- a. $\frac{4}{3}k\Omega$
- b. 1kn
- $c.\frac{3}{4}k\Omega$
- d. $\frac{7}{4}k\Omega$

13. The output voltage of the opamp shown in Fig. 13 has a value



- a. -12V
- b. 10V
- .c. 12V
- d. 24V

14. The high and low cut-off frequencies of an amplifier can be determined by the response of the system to

a. sinusoidal input

b. square wave input

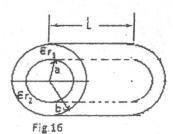
c. triangular wave input

d. pulsed input

The number of machine cycles and T states required for execution of STA instruction are

- a. (3, 12)
- b. (4, 12)
- c. (4, 13)
- d. (3, 13)

16. The capacitance of a cylindrical capacitor of length 'L' and each dielectric occupies one half of the volume shown in Fig. 16 is



$$a. \ \frac{4\pi \in_0 (\epsilon_{r1} + \epsilon_{r2})L}{\ln \frac{b}{a}} \quad b. \ \frac{\pi \in_0 (\epsilon_{r1} + \epsilon_{r2})L}{\ln \frac{b}{a}} \quad c. \ \frac{8\pi \in_0 (\epsilon_{r1} + \epsilon_{r2})L}{\ln \frac{b}{a}} \quad d. \ \frac{2\pi \in_0 (\epsilon_{r1} + \epsilon_{r2})L}{\ln \frac{b}{a}}$$

b.
$$\frac{\pi \in_{0} (\varepsilon_{r1} + \varepsilon_{r2})I}{\ln \frac{b}{\epsilon}}$$

c.
$$\frac{8\pi \in_{0} (\varepsilon_{r1} + \varepsilon_{r2})I}{\ln \frac{b}{a}}$$

d.
$$\frac{2\pi \in_0 (\varepsilon_{r_1} + \varepsilon_{r_2})L}{\ln \frac{b}{a}}$$

17. The logic function $y = \overline{A}(\overline{B} + C) + A\overline{B}C$ can be expressed in its simplest form

a. $y = \overline{A}(\overline{B} + C) + A\overline{B}C$

b. $y = \overline{B}(\overline{A} + C) + \overline{A}C$

c. $v = \overline{A}(\overline{A} + C) + B\overline{A}C$

d. $v = \overline{A}(\overline{B} + \overline{C}) + A\overline{B}$

18. The program to load the flag register contents to C register is

- a LXI SP, 27FCH **PUSH PSW** POP B
- b. LXI SP, 27FCH **PUSH PSW** POP D
- c. LXI SP, 27FFH **PUSH PSW** POP B
- d. LXI SP, 27FEH **PUSH PSW** POP B

19. The following program results in

LXI SP, 27FEH

PUSH B

PUSH D

POP B

POP D

- a. exchanges contents of BC and DE
- b. stores original contents of BC and DE in stack
- c. exchanges contents of BD and CE
- d. stores contents of only BC in DE

20. The following is not a vectored interrupt

- a. TRAP
- b. RST 5.5
- c. INTR
- d. RST 7.5

21. The vector address for RST4 is

- a. 0018H
- b. 0020H
- c. 0028H
- d. 0030H

22. The control word for 8255 in model with Port A as input port is

- a. 10111
- b.11101
- c.01110
- d. 11011

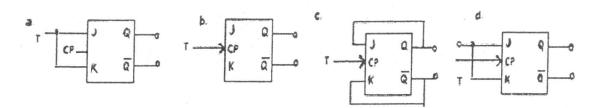
23. In order to get correct answer when two numbers are added in Excess- 3 code and sum is less than 9, it is necessary to

- a. To subtract 0011 from the sum
- b. to add 0011 to the sum
- c. To subtract 0110 from the sum
- d. to add 0011 to the sum

24. The open loop gain of an amplifier is 100. If negative feedback with $\beta = 0.1$ is used the closed loop gain will be

- a. 111.1
- b. 90.9
- c. 0.09
- d. none of these

25. The following circuit converts a JK Flip Flop into a T Flip Flop.



- 26. The efficiency of a transformer -coupled Class A amplifier for a supply of 12 V and Output of 6V is
 - a. 50%
- b. 12.5%
- c.1.39%
- d. 0.26%

27. The quality factor Q of a piezoelectric crystal has a typical value of

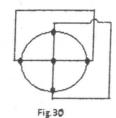
- a.5000
- b.1000
- c. 10,000
- d. 20,000

28. At time $t = 0^+$ with zero initial condition, the following element acts as a open circuit

- a. inductor
- b. capacitor
- c. resistor
- d. all of these

- 29. $H(s) = \frac{v(s)}{I(s)} = \frac{4s+6}{s+2}$ when i(t) is a unit step function as t tends to infinity is given by the value of v(t) is
 - a.0

- b. 3
- c. 4
- d. 80
- The number of branches and nodes in the given graph Fig.30 are



- a. (5,10)
- b.(8,5)
- c.(10,5)
- d.(6,10)

(Common to EE/EC/TC/BM/ML/IT)

SECTION - II of PART - A

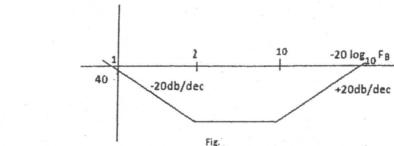
Each question carries Two marks

 $15 \times 2 = 30 \text{ Marks}$

- Resonance peak M_p and resonant frequency ω_p for the system $\frac{C(s)}{R(s)} = \frac{s}{(s^2 + 2s + 1)}$ are
 - a. $\frac{3}{4}, \pm \sqrt{3}$
- b. $\frac{1}{2}, \pm \sqrt{2}$ c. $\frac{1}{4}, \pm \sqrt{3}$
- d. $\frac{5}{4}$, $\pm\sqrt{3}$

The departure angle of the root locus from pole at
$$s = -10 + j10$$
 for
$$GH = \frac{K(s+8)}{(s+14)(s+10+j\omega)(s+10-j10)}$$
 for $K > 0$ is a. 132° b. 124° c. 72°

- d. 66°
- The transfer function of a minimum phase system with Bode plot shown in Fig., is



- a. $G(j\omega) = \frac{100\left(1 + \frac{j\omega}{2}\right)\left(1 + \frac{j\omega}{10}\right)}{j\omega}$
- c. $G(j\omega) = \frac{\left(1 + \frac{j\omega}{2}\right)\left(1 + \frac{j\omega}{10}\right)}{10}$
- b. $G(j\omega) = \frac{10\left(1 + \frac{j\omega}{2}\right)\left(1 + \frac{j\omega}{10}\right)}{\underline{j\omega}}$
- d. $G(j\omega) = \frac{100\left(1 + \frac{j\omega}{2}\right)\left(1 + \frac{j\omega}{10}\right)}{j\omega}$

34. The closed loop transfer function of the system represented by the state model is given by

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -3 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} \frac{40}{3} \\ -15 \\ \frac{5}{3} \end{bmatrix} U \text{ and } [Y] = \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

a.
$$\frac{10(s+4)}{s(s+1)(s+3)}$$

a.
$$\frac{10(s+4)}{s(s+1)(s+3)}$$
 b. $\frac{20(s+4)}{s(s+1)(s+3)}$ c. $\frac{-5(s+4)}{s(s+1)(s-3)}$ d. $\frac{-15(s+4)}{s(s+1)(s-3)}$

c.
$$\frac{-5(s+4)}{s(s+1)(s-3)}$$

d.
$$\frac{-15(s+4)}{s(s+1)(s-3)}$$

The minimum cost POS expression for the function $f(x_1,x_2,x_3) = \sum m(1,2,3,5)$ is

a.
$$f = (\overline{x_1} + \overline{x_2})(x_2 + x_3)$$

b.
$$f = (\overline{x_1} + \overline{x_2})(x_1 + x_3)$$

d. $f = (\overline{x_3} + \overline{x_2})(x_2 + x_3)$

c.
$$f = (\overline{x_1} + \overline{x_3})(x_2 + x_3)$$

d.
$$f = (\overline{x_3} + \overline{x_2})(x_2 + x_3)$$

36. The following program in 8253/54 with control register address=0BH, counter 0=08H, counter 1=09H and counter 2=0AH.

MVI A, B 0H

Out 0BH

MVI A, low byte (30H)

Out 0AH

MVI A, high byte (C0H)

Out 0AH

a. Initializes Counter 2 in mode 0 with a count of C030H

b. generates a square wave of lkHz

c. generates a real time clock

d. provides a delay of 5 secs

37. The following set of instruction checks

RIM

ANI 10 H

CNZ 002CH

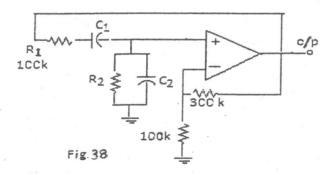
a. RST 7.5 is pending

b. RST 5.5 is individually masked

c. disables RST 5.5

d. RST5.5 is pending

38. The value of the capacitors C_1 and C_2 in a Wein bridge oscillator in Fig38 for $f_0 = 10khz$ are



a. (159pF,159pF)

b. (159μF,159μF) c. (169pF,159pF) d. (150mF,169mF)

39. The value of (V_{CEQ}, I_E) for the circuit in Fig39 is given by

$$V_{1} = \begin{cases} C_{1} & 10 \mu F \\ V_{2} & C_{2} & 10 \mu F \\ R_{B} & 240 k \\ \hline = & 2 k \end{cases}$$

$$V_{EE} = -20 \text{ V}$$

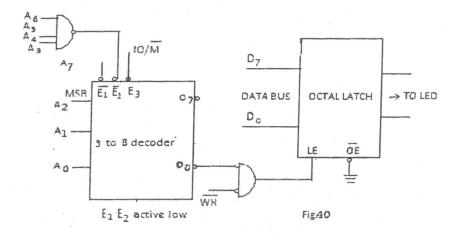
a. (11.68mV, 4.12mA)

b. (10.68mV, 45.73μA)

c. (20.63mV, 4.16µA)

d. (11.68V, 4.16mA)

40. The Port address and mapping scheme for Fig.40 are



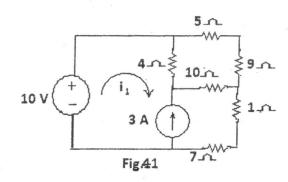
a. I/O mapped I/O,78H

b. Memory mappedI/O, 78 H

c. I/O mapped I/O,68H

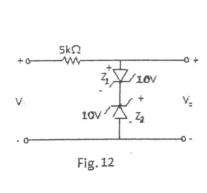
d. Memory mappedI/O, 88 H

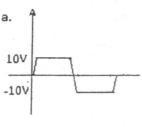
41. The magnitude of current i_1 in the circuit shown in FigA1 is

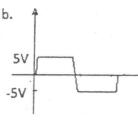


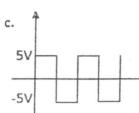
- a. 1.93 A
- b. 2.93 A
- c. 1.93 A
- d. 2.93 A

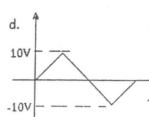
42. The output waveform of the circuit in Fig 42 for a sinusoidal input of peak 50V is



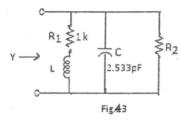




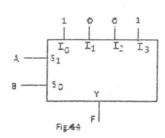




43. The value of the inductance 'L' for a resonant frequency of 1MHz for the circuit in Fig A3 is

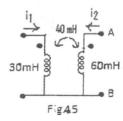


- a. 1mH
- b. 0.1mH
- c. 100mH
- d. 10mH
- 44. The function implemented by the multiplexer chip of fig. 44 is



- a. $F(A, B) = A \oplus B$
- c. $F(A, B) = \overline{A}B$

- b. F(A, B) = AOB
- d. $F(A, B) = \overline{A}B + AB$
- 45. The voltage V_{AB} for the circuit in Fig.45 is given by



- a. 13.33 cos1000t
- b. 13.33 sin1000t
- c. 23.33 cos100t
- d. 13.33 cos100t

NOTE:

Each Question Carries One Mark

(c) armature current

PLEASE CHOOSE TO ANSWER PART – B BELOW CORRESPONDING TO YOUR BASIC DEGREE

 $20 \times 1 = 20 \text{ Marks}$

PART – B (EE: ELECTRICAL AND ELECTRONICS ENGINEERING) SECTION – I OF PART – B

46. Fleming's left hand rule is applicable to (a) dc generator (b) dc motor (d) transformer (c)alternator 47. Neglecting all losses, the developed torque (T) of a DC separately excited motor, operating under constant terminal voltage, is related to its output power (P) as under (c) $T^2 \alpha P^3$ (a) T $\alpha \sqrt{P}$ (b) T α P (d) T is independent of P **48.** The speed regulation of a dc motor is given as (a) N_0 - N_f (b) N_0/N_f (c) $(N_0-N_f)/N_f$ (d) $(N_0 - N_f)/N_0$ 49. The efficiency of a power transformer is around (b) 60% (c) 80% (a) 50% (d) 95% 50. If rated dc voltage is applied instead of ac to the primary of a transformer (b) primary of transformer will burn (a) secondary of transformer will burn (c) secondary voltage will be excessively high.(d) there will be no secondary voltage. 51. If the applied voltage of a certain transformer is increased by 50% and the frequency is reduced to 50% (assuming that the magnetic circuit remains unsaturated), the maximum core flux density will (a) change to three times the original value (b) change to 1.5 times the original value (c) change to 0.5 times the original value (d) remain the same as the original value. **52.** Core loss in a transformer is usually (a) 1% to 3% (b) 10% to 15% (c) 25% to 30% (d) 40% to 50% 53. In a synchronous machine, if the field flux axis is ahead of the armature field axis in the direction of the rotation, the operating machine is a (a) synchronous motor (b) synchronous generator (c) asynchronous motor (d) asynchronous generator 54. Variation in dc excitation of a synchronous motor causes variation in (a) speed of motor (b) power factor

(d) both (b) and (c).

55.	Feeder is designed mai (a) its current carrying (c) operating voltage		iew of (b) voltage drop in it (d) operating frequen	су
56.	In a transmission syste (a) E ²	m, the weight of coppe (b) E	r used is proportional (c) 1/E ²	to (d) 1/E
57.	In a vacuum circuit bre (a) 1 torr	eaker, the vacuum is of (b) 10^{-6} torr		(d) 10 ⁻¹⁶ torr
58.	At a room temperature (a) 3V, 40mA	of 30 °C, minimum vo (b) 0.6V, 40 mA		uired to fire a SCR is (d) 3V, 100mA
59.	(a) flat voltage profile(b) transmission line and	nted with its surge imposingle greater than actual ngle less than the actual	length of line	
60.	-	awn from the bus	t the bus	
61.	The unit protection sch (a) primary protection (c) simultaneous protection		(b) backup protection (d) remote protection	
62.	(c) a decrease in the me		ne machine	creased by
63.	The plant suitable for (a) Diesel engine plant (c) Nuclear power plant	•	(b)Steam power plan (d)Hydro-electric pla	
64.	The recovery voltage v (a) zero	vill be maximum for po (b) 0.5	ower factor of (c) 0.707	(d) unity
65.	The extremely high inp (a) absence of its chance (b) depletion of current (c) extremely small lead (d) everyore	nel		ause of

(EE: ELECTRICAL AND ELECTRONICS ENGINEERING) SECTION – II OF PART – B

66. The armature resistance of a 6 pole lap wound dc machine is 0.05Ω . If the armature is rewound

Each Question Carries	Two	Marks
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 $10 \times 2 = 20 \text{ Marks}$

	* * * WISH YOU GOODLUCK * * *				
	be (a) 3.32 V	(b) 5√2 V	(c) 10V	(d)10√2 V	
75.		ctify a sine wave of 10	V_{rms} , the minimum be	reak in voltage of diode should	
74.		l, the maximum value ll be		from an infinite bus. If the load ing of the rotor around its new (d) 25 ⁰	
73.		connected in the neu	tral, $x_n=0.05$ pu. and	in phase a. If $x_d=x_2=0.25$ pu., the initial prefault voltage is (d) 1.25pu	
72.	When a line commutate (a) draws both real and (b) delivers both real ar (c) delivers real power (d) draws reactive power	reactive power from the reactive power to the to the AC supply	he AC supply e AC supply		
71.	A 3 phase, fully control The rms current through (a)50A		converter is	d at a constant current of 150A. (d) $150/\sqrt{3}$	
70.		eaker is to operate at	_	50:1. If the normal line current ent, the trip mechanism should (d)none of these	
69.	If the percentage resis ratio is 1:10, the perce (a) 25	•		ry side is 2.5 percent and turn ry will be (d) 0.025	
68.	1 KVA, 230V, 50 Hz, current loss when the tr (a) 30 watts	ransformer is excited b			
67.	critical resistance of th	e machine was $80~\Omega$. enerator just failed to g	Due to some reasons	ng normally at 1000 rpm, the sthe speed of the prime mover that time must have been (d) 500rpm	
	using a wave winding t (a)0.45	hen the armature resist (b) 0.30	tance will be (c) 0.15	(d)0.10	

PART - B

(EC & TC: ELECTRONICS AND COMMUNICATION ENGINEERING AND TELECOMMUNICATION ENGINEERING) SECTION – I OF PART – B

Each question carries one mark

 $20 \times 1 = 20 \text{ Marks}$

46.	Response is the measura. Quickness of the syb. How fast the system. Both a & b. None of these	ystem	the input	
47.	Which of the following a. C	g is the hardware descr b. Verilog	iption language? c. VHDL	d. Both b & d
48.	Which of the following a. The emitter of the to b. The collector of the c. The emitter of the to d. Both a & c	ransistor is grounded transistor is grounded	ollector configuration?	
49.	In embedded hardware a. A soft form of reprib. Software 'Blueprin' c. Both a & b d. None of these	esentation of the PCB		aponents in a hardware
50.	The file inclusion pre-pa. #define	b. #include	c. #ifdef	d. None of these
51.	The memory managem allocated memory bloca. malloc()			cated bytes in a dynamically d. free()
52.	GPRS communication a. 2	divides the ratio channels. 3	nel into timesle	ots. d. 8
53.	The architecture which a. Harvard	supports easier impler b. Von Neumann	nentation of the pipeli c. Both a & b	ning is d. None of these
54.	All the conditional brar a. Relative offset meth c. Either a or b		b. Absolute address d. None of these	*
55.	An n-channel JFET has region and the drain cur a. 1.88 mA	_		num value of Vds for Pinch-off region, is d. 2.55 mA

56.	A dual beam CRO has a. Two horizontal ample. Two vertical ampli	olifiers	b. Two trigger circud. All of these	its
57.	In the operation of half by the valua. decreasing, decreasing, decreasing.	ne of the filter capaciton		asing
58.	Mouse that is used in a a. Software	nny PC works on the pr b. Hardware	_	d. All of these
59.	UNIX / Linux Operational Monolithic	_ ,	The state of the s	d. None of these
60.		d bias current if the		ceived by a 50-ohms antenna. the amplifier must "match" the d. 0.55mA
61.	_	m allowable base voil current? Assume Vo	Itage if the different $c = 2.5V$.	a collector resistance of $1 \text{ k}\Omega$ ial input is large enough to d. None of these
62.	An inverter must exhibit the gain of the circuit is a. 30			he supply voltage is 1.8V, d. 3.6
63.	A type of memory, whistance in a single cyca. Boot Flash	le, is	es that is erasable made. EEPROM	ny times in a flash at the same d. OTP
64.	The SNR are modulating-signal freq	uencies.	ating-signal frequencie	
65.	Which of the following a. Routers	g forward broadcasts of b. Bridges		

(EC & TC: ELECTRONICS AND COMMUNICATION ENGINEERING AND TELECOMMUNICATION ENGINEERING) SECTION – II OF PART – B

Each question carries two marks

 $10 \times 2 = 20 \text{ Marks}$

66.				y of a full-wave center tapped V, the maximum PIV rating of
	a. 199.3 V	b. 190.3 V	c. 109.3 V	d. 99.3 V
67.	The bypass capcitor ac a. Increases the emitte c. Improves the stabil	er current	nce: b. Increases the outp d. Improves the gain	
68.	In voltage divider bias, a. $200 \text{ k}\Omega$	operating point is 3V, b. $400 \text{ k}\Omega$	2 mA. If $Vcc = 9 \text{ V}$, c. $800 \text{ k}\Omega$	Rc = 2.2 k Ω , the value of Re is d. 1600 k Ω
69.	resistance will be:			$Rg = 1 M\Omega$. The total input
	a. 1666 Ω	b. 166.6 Ω	c. 1 Ω	d. 10666.6 Ω
70.	If the differential and then the CMRR will be		of a differential ampli	fer are 50 and 0.2 respectively,
	a. 10	b. 49.8	c. 50.2	d. 250
71.	An AND gate is a a. Sequential circuit c. Memory circuit		b. Combinational circ	
72.	The energy stored in a volts is	1000uF capacitor at t =	= 50 microsec, if the vo	oltage across it is 1.5cos10 ⁵ t
	a. 80.52 uJ	b. 90.52 uJ	c. 100.52 uJ	d. 99.52 uJ
73.	interval $10 < t < 20$ m thereafter. Assume the	is; is 0 for $20 < = t < 0$	< 30 ms; is 100V for n for vL and iL. Find i	lecreases linearly to zero in the 30 < t < 40 ms; and is zero L at t= 8ms, if iL (0) = -2A. d. 5 A
74.	A volatage waveform $7u(t) - 0.2u(t) + 8u$ 3.5u(t) - 0.1 u(t) + 4u(t a. 2-ohms resistance	(t-2) + 3 V. If $t-2 + 1.5$ A, what type	the corresponding cur of element is it, and w	rrent through that element is that is its value?
75.	D, are connected in seri if $A = C = 10V$, $B = D$	es with a 4-ohms Resisted = 0V.	stor. Find the average p), C cos 40t and the constant power dissipated in the resistor
	a. 20 W	b. 25 W	c. 50 W	d. 15 W
		*** WISH VOII	COODLIICK ***	

PART-B

(BM & ML : BIOMEDICAL ENGINEERING & MEDICAL ELECTRONICS) SECTION - I OF PART - B

Each question carries one mark

 $20 \times 1 = 20 \text{ Marks}$

46. The time required for cell to return to its pre-stimulus state is known as a. Stimulus threshold b. Refractory period c. Critical time d. Excitation time 47. In which mode of ECG machine stilus moves in response to input signal but the paper is stationary? a. Standby mode b. Pericardial mode c. Augmented mode d. Isolated mode 48. In Balke-Wave Protocol used in treadmill test, the constant speed used is a. 4.6 miles/hour b. 6.8 miles/hour c. 3.3 miles/hour d. 1.2 miles/hour 49. The device which gives external stimulus to heart muscles to regulate heart beats is known as a. Defibrillator b. Pacemaker c. ECG machine d. Electrosurgical unit **50.** The coronary vessels of heart are examined using a. Angio cardiograph b. Coronary angiography c. Cerebral angiography d. Fluoroscopy 51. The unit of radioactivity is a. Peri b. Rem c. Curie d. Rontegen The Planck's equation is given by a. E=hwo b. $E=\sqrt{Bo}$ c. $E=(hwo)^2$ d. $E=(\sqrt{Bo})^2$ 53. Common scan used in echo cardiograph is a. Linear scan b. Sector Scan c. Compound Scan d. None of these 54. A signal is periodic with period T if x(t) equals a. x(-t)b. x(1/t)c. x(t+T)d. x(T)

- 55. Any periodic function can be expressed by a Fourier series when the function has
 - a. Infinite number of finite discontinuities in a period
 - b. Finite number of infinite discontinuities in a period
 - c. Finite number of finite discontinuities in a period
 - d. Infinite number of infinite discontinuities
- **56.** In DIF FFT diagram
 - a. Input data appears in the bit reversed order
 - b. The power r of W_N is a variable which depends on the position of butterfly in flow diagram
 - c. Frequency domain values are in natural order
 - d. All the above three
- 57. Bilinear transformation is defined by the substitution

a.
$$S = 2/t [1-z^{-1}/1+z^{-1}]$$

b.
$$S = 1 - z^{-1} / T$$

c.
$$S = ze^{sT}$$

d.
$$S = e^T$$

58.	The duration of P wave a. SA Node	b. Ventricles	through c. Bundles of HIS	d. Atria
59.		n where a normal bea	t is followed by two pr	remature beats and one full
	compensatory pause is a. Brady cardia	b. Tachycardia	c. Bigeminy	d. Trigeminy
60.	Transducer used to acq a. LVDT	uire PCG signal is b. LDR	c. Microphone	d. RTD
61.	The Minimum number a. 1	of leads simultaneous b. 2	ly used in holter monit c. 3	oring is d. 4
62.	One among the oldest sa. X-rays	ources of EM radiatio b. Gamma rays		d. Microwaves
63.	A body that reflects lig-	ht and is relatively bal	anced in all visible wa	velength appears to the
	a. Black	b. White	c. Colored	d. None of these
64.	Smoothing spatial filter a. Blurring		c. Both a and b	d. None of these
65.	A spatial average filter a. Round	in which all coefficier b. Square	nts are equal is sometime. Box	nes called d. Rectangle
(BM & ML : BIOME		ERING & MEDIO	CAL ELECTRONICS)
Eac	h question carries Two	marks		$10 \times 2 = 20 \text{ Marks}$
66.	The NMR imaging coura. Heating due to rf poc. Electric current indu	ower	th hazard due to b. Static magnetic fid. All of these	eld
67.	The N-term Bartlett win a. $w(n) = \{1,0 \le n \le N-1\}$ c. $w(n) = \{0.5-0.5 \text{ Co}\}$, 0, else where	b. $w(n) = \{1-2 n-(N-d) + (N-d) = 0.54 - 0.46\}$	
68.	The continuous time LT a. $h(t) = 0$, for $t=0$	*	c. $h(t) = 0$. for $t < 0$	d. $h(t) = 1$, for $t < 0$
69.	Z transform of $x(n+n_0)$ a. $Z^{-no} X(Z)$		c. X (Z + Zo)	d. X (Zo)

71.	The standard clinical ve a. 2	b. 3	reads c. 4	d. 12
72.	A Speech signal is segma. Parametric Model c. Markov Model	nented into elementar	y patterns like word an b. Phenomenologica d. Prony's model	d phoneme using model called l model
73.	If the compression ratio a. 0.99	of a given image is 1 b. 0.099	.11 then the level of rec. 0.88	dundancy will be d. 0.088
74.	The response of derivati	ive operators in an are b. Two	ea of constant gray leve c. Zero	el would be d. None of these
75.	Ultrasonic directional D a. Singe side bond c. Phase quadrature det		b. Heterodyne d. All of these	hieved using
		* * * WISH YOU	GOODLUCK **	k
	(IT:	INSTRUMENTA	RT – B TION TECHNOL I OF PART – B	LOGY)
Eac	n question carries one m	ark		$20 \times 1 = 20 \text{ Marks}$
46.	Seismic type of transduc	er has a damping con	stant of 10. The transd	lucer is designed to measure
46.			stant of 10. The transd c. Displacement	
46.47.		b. Velocity	c. Displacement	d. Force
	a. Acceleration	b. Velocity s for balls and rollers	c. Displacement	d. Force s are bon steel
	a. AccelerationThe most suitable metalsa. Mild steel	b. Velocity s for balls and rollers on steel	c. Displacementof antifriction bearingsb. Hardened low carl	d. Force s are bon steel
47.	a. AccelerationThe most suitable metalsa. Mild steelc. Hardened high carbo	b. Velocity s for balls and rollers on steel	c. Displacementof antifriction bearingsb. Hardened low carl	d. Force s are bon steel um steel
47.	 a. Acceleration The most suitable metals a. Mild steel c. Hardened high carbo An integral control is use a. Improve the transien 	b. Velocity s for balls and rollers on steel ed to t response	c. Displacement of antifriction bearings b. Hardened low carl d. Hardened Chromi b. Reduce the offset d. Reduce the settling	d. Force s are bon steel um steel
47. 48.	 a. Acceleration The most suitable metals a. Mild steel c. Hardened high carbo An integral control is use a. Improve the transien c. Eliminate the offset 	b. Velocity s for balls and rollers on steel ed to t response	c. Displacement of antifriction bearings b. Hardened low carl d. Hardened Chromi b. Reduce the offset d. Reduce the settling	d. Force s are bon steel um steel g time utomobile emission is
47. 48.	a. Acceleration The most suitable metals a. Mild steel c. Hardened high carbo An integral control is use a. Improve the transien c. Eliminate the offset The method widely acce a. Orsat analysis c. Chemi-luminiscence	b. Velocity s for balls and rollers on steel ed to t response pted to determine oxi	c. Displacement of antifriction bearings b. Hardened low carl d. Hardened Chromi b. Reduce the offset d. Reduce the settling des of nitrogen in an ar b. Gas-chromatograp d. Flame-ionization continuation is provided	d. Force s are bon steel um steel g time utomobile emission is ohy detection d with a shield while taking

51.	A real function f(t) h	as a Fourier transform	$F(\omega)$. The Fourier trans	sform of $[f(t)-f(-t)]$ is
	a. Zero	b. Real	c. Real and odd	d. Imaginary
52.	A Pirani gauge senso	or is used to measure pr	ressure of the order of	
	a. 10MPa	b. 1MPa	c. 100Pa	d. 1Pa
53.		nction of a system ha e encirclement of (-1, 0		of the s-plane. The Nyquist plot op system is
	a. Unstable	b. Stable	c. Marginally stab	le d. Asymptotically stable
54.	The dominant poles	of a sevosystem are loc	eated at $S = (-2\pm j2)$. The	ne damping ratio of the system is
	a. 1	b. 0.8	c. 0.707	d. 0.6
55.				v into a bath of boiling water at ch a temperature of 98° C is
	a. 32.5s	b. 34.6s	c. 35.6s	d. 38.6s
56.	Which of the follow	ing sequences is NOT a	a power signal?	
	a. Unit step sequenc. A periodic seque		b. e ^{j α n}d. Unit ramp sequ	ence
57.	The discrete LTI sys	tem with this impulse i	response is non-causal	
	a. a ⁿ u (n-2)	b. a ⁿ⁻² u (n)	c. $a^{n+2} u(n)$	d. a ⁿ u (n+2)
58.	A pitot-static tube is proportional to	used for measuring ve	locity of a gas, flowing	g in a duct. The velocity is
	b. The total pressurc. Difference between	e total pressure measure e measured by the tube een total and static pres fference between total	sure	
59.	Which of the follow	ng instruments uses an	ultrasonic transducer	?
	a. Echo-cardiograpc. Electro-encephal		b. Electro-cardiogd. None of these	raph
60.	Among the electrode is placed at,	es which are used to rec	cord ECG signals, the	one used for ground referencing
	a. Left arm	b. Right leg	c. Left leg	d. Right arm
61.	Which of the follow	ing restrictors has the h	ighest discharge co-ef	ficient?
	a. Orifice plate	b. Flow nozzle	c. Venture tube	d. None of these

	c. Two primary coils	connected in opposition and two secondary co	d a secondary coil on and a secondary coil ils connected in phase ils connected in opposi	
63.	The measurements of a the readings is equal to		9V, 5.7V and 6.1V. Th	e sample standard deviation of
	a. 0.013	b. 0.04	c. 0.115	d. 0.2
64.	Stop band attenuation	of Hamming window	will be,	
	a. 53 dB	b. 25 dB	c. 74 dB	d. 44 dB
65.	A Butterworth filter ha	as		
	a. Very smooth transc. Very smooth pass l		b. Very smooth stopd. None of these	band
	(IT		ATION TECHNOI II OF PART – B	LOGY)
Eac	h question carries Two	marks		$10 \times 2 = 20 \text{ Marks}$
66	A DID controller has the	na transfer function 24	0.4 with the unit of tir	ne expressed in minutes. The
66.			for the above controlle	
			c. 200% and 5 min	
67.	A 3 ¹ digit multi-meter	has an accuracy speci	fication of 0.5% of read	ding plus 5 counts. The value of
	*			er. The value of resistance is d. $50\pm1.0~\Omega$
68.		nge is 12 mm away fro	•	nown monochromatic source of the screen distance is 0.8 m,
				d. 750 nm
69.	Sensitivity drift = 0.01	n temperature = 10V/I (V/MPa)/deg cel	MPa, zero drift = 0.01V	
	device is 7.4 V. The tr	ue value of the pressur	re will be	erature, the output from the
	a. 0.71 MPa	b. 0. 68 MPa	c. 0.65 MPa	d. 0.61 MPa
70.				rain condition. A 200k Ω fixed resent an equivalent strain of d300 μ m/m.
		F	S-10	

62. Linear variable differential transformer has

71.	specimen, an ech	V 1	ed 0.05 mass after t	a frequency of 330 kHz. Whithe transmitted pulse. If the thof	
	a. 120 cm	b. 60 cm	c. 30 cm		
72.	A certain closed l	oop system with unity	feedback has a forv	ward path transfer function	given by

- 72. A certain closed loop system with unity feedback has a forward path transfer function given by $G(s) = \frac{K}{s(s+1)(s+5)}$. With the gain set at the ultimate value, the system will oscillate at an angular frequency of
 - a. $\sqrt{6}$ rad/s
- b. $\sqrt{5}$ rad/s
- c. $\sqrt{2}$ rad/s
- d. $\sqrt{3}$ rad/s
- 73. The fundamental period of the sequence $x[n] = 3\sin(1.3\pi n + 0.5\pi) + 5\sin(1.2\pi n)$ is
 - a. 20
- b. $\frac{2\pi}{1.3\pi}$
- $C. \frac{2\pi}{1.2\pi}$
- d. 10
- 74. The output from a 633 nm He-Ne laser comes out from the mirror with a beam diameter of 1 mm and diverges to the far field. It is brought to a focus by convex lens of focal length of 17 mm. the spot size diameter of the beam at the focal point is
 - a. 20 µm
- b. 26 μm
- c. 52 µm
- d. 13 µm
- 75. A thermocouple is made using a copper and iron wire. Its measuring junction is kept at a temperature of 100° C and the reference junction is kept at the ambient temperature of 30° C. The emf developed would be
 - a. 700 μV
- $b.\ 1000\ \mu V$
- c. 3010 µV
- d. 5300 µV

* * * WISH YOU GOODLUCK * * *